21-25 March 2022 Boulder (CO), USA Machine Learning in Heliophysics

Applications of Image Translation Methods Based on Deep Learning to Solar Data

Eunsu Park

Kyung Hee University, South Korea / espark@khu.ac.kr

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Introduction

Sun and Space Weather Group in Kyung Hee University

We have applied deep learning (DL) to various types of solar and space weather data and tasks

Our goal:

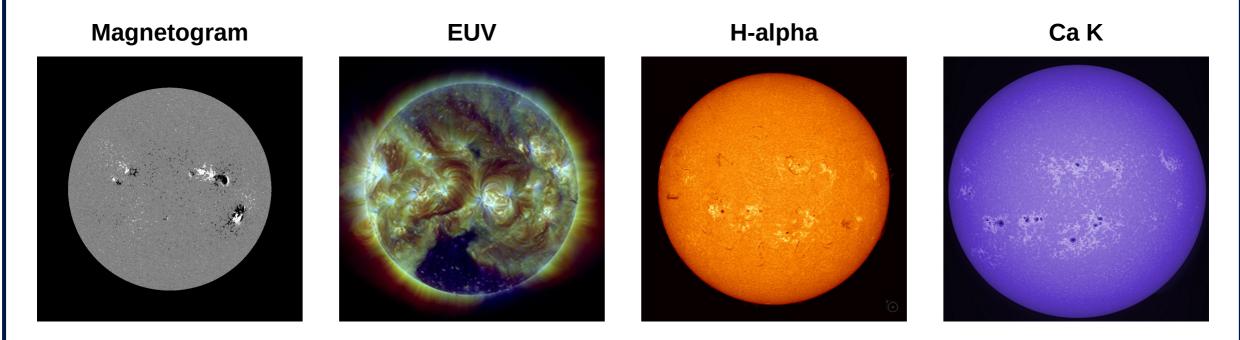
- 1) To improve space weather prediction models
- 2) To fill in observation blanks
- 3) To calibrate observational data such as denoising
- 4) To study whether DL-generated data are feasible for scientific data or not

Recently, we have applied image translation methods based on deep learning to various solar and space weather data.



0 Introduction

Why image translation?



There are various types of multi-filter observations in solar and space weather, and many of them are observed simultaneously.

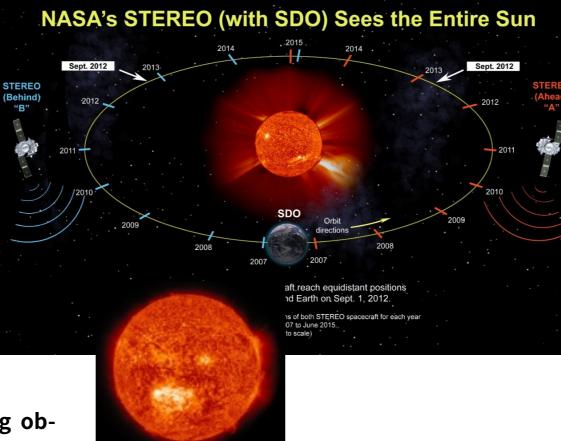
-> It is a good condition for applying the image translation algorithms.



Generation of Solar Far-side Magnetograms from STEREO/EUVI Images

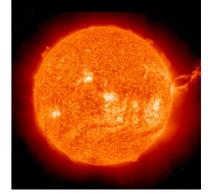
> Kim, Park, Lee et al., 2019 Jeong et al., 2020 Park et al., 2021





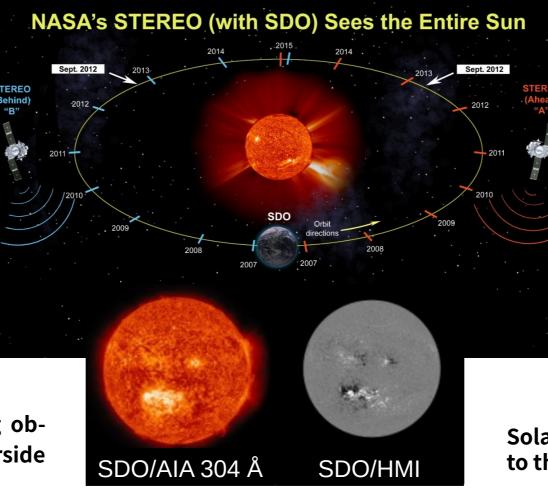
SDO/AIA 304 Å

STEREO A EUVI 304 Å



Solar EUV images are being observed from the front and farside of the Sun



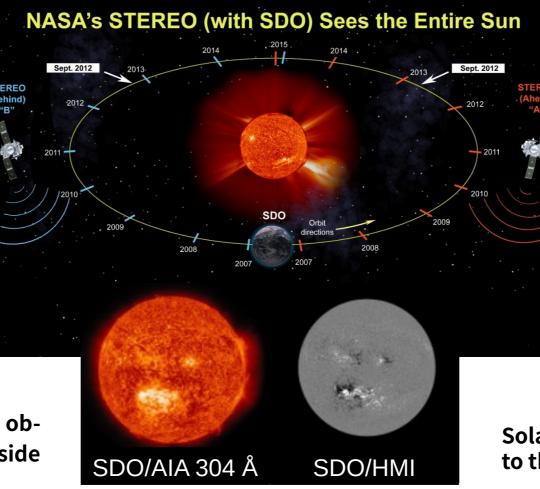




Solar EUV images are being observed from the front and farside of the Sun

Solar magnetograms are limited to the frontside solar disk



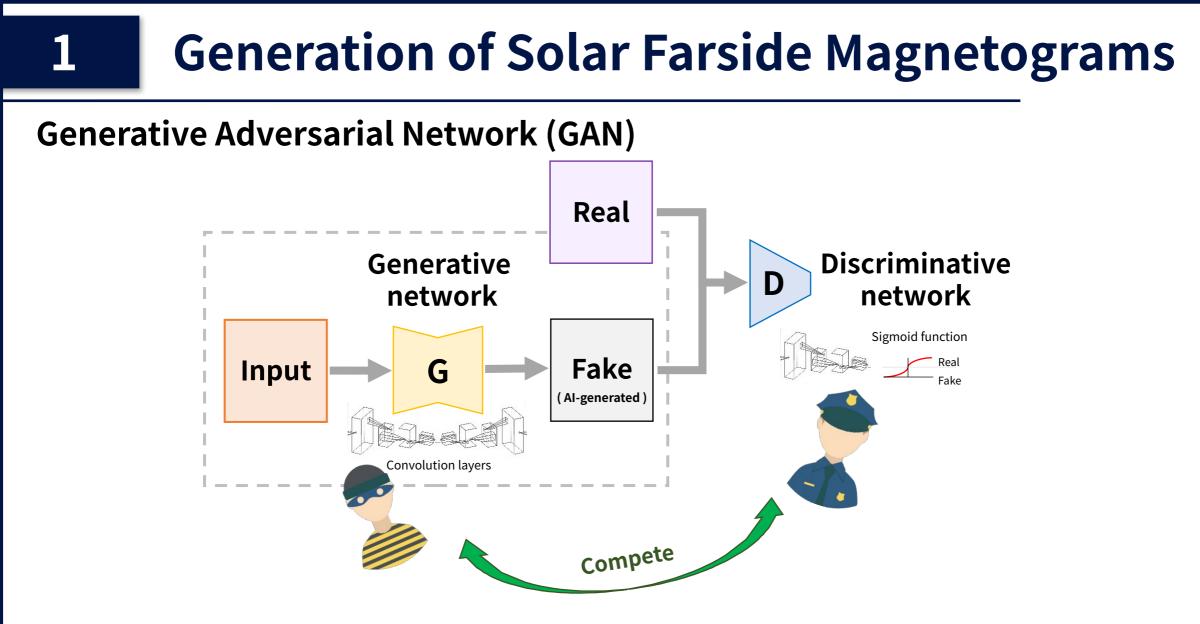




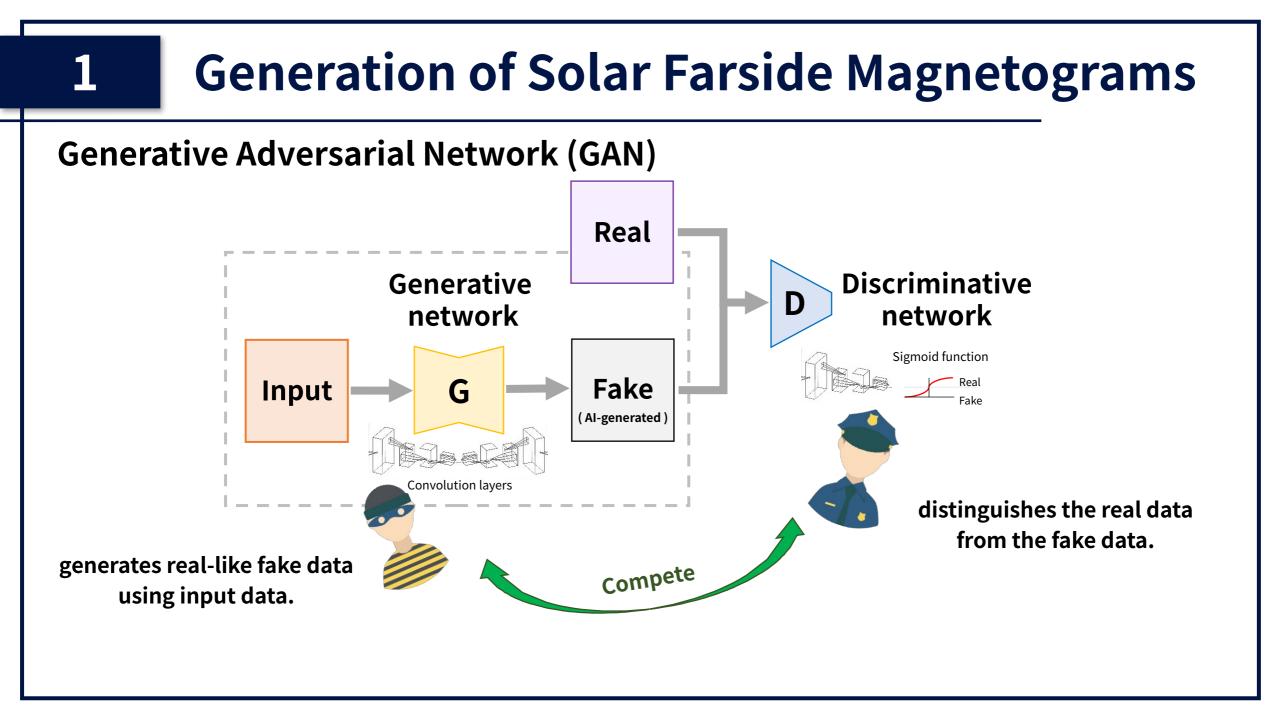
Solar EUV images are being observed from the front and farside of the Sun

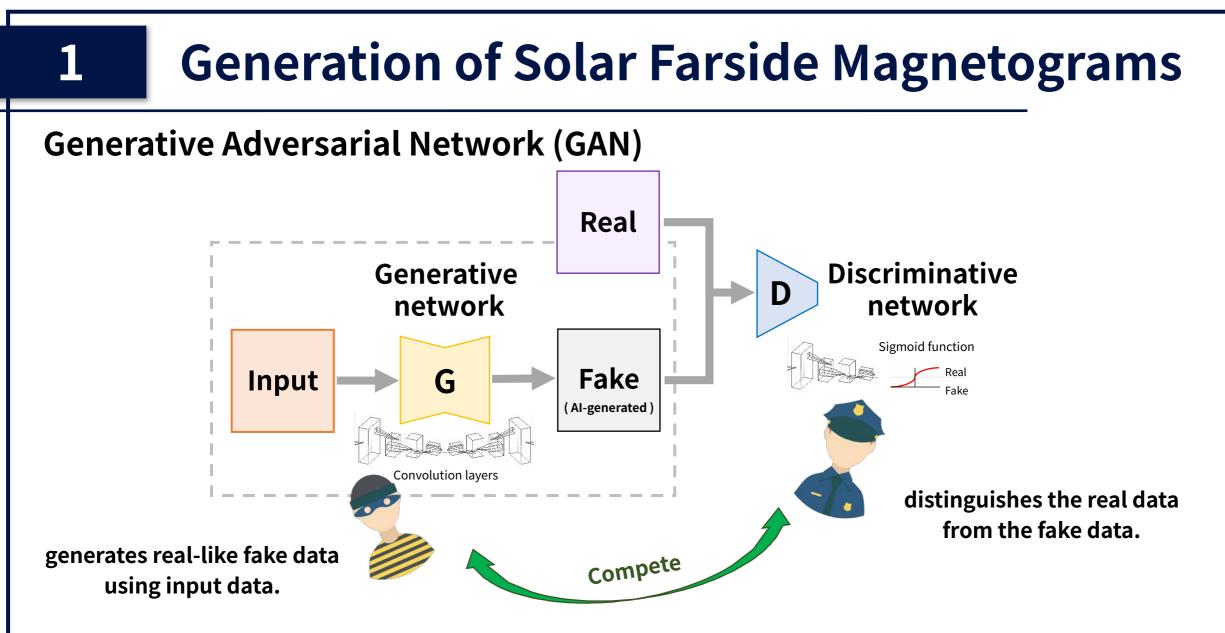
Solar magnetograms are limited to the frontside solar disk

We design a model for the translation from solar EUV images to solar magnetograms

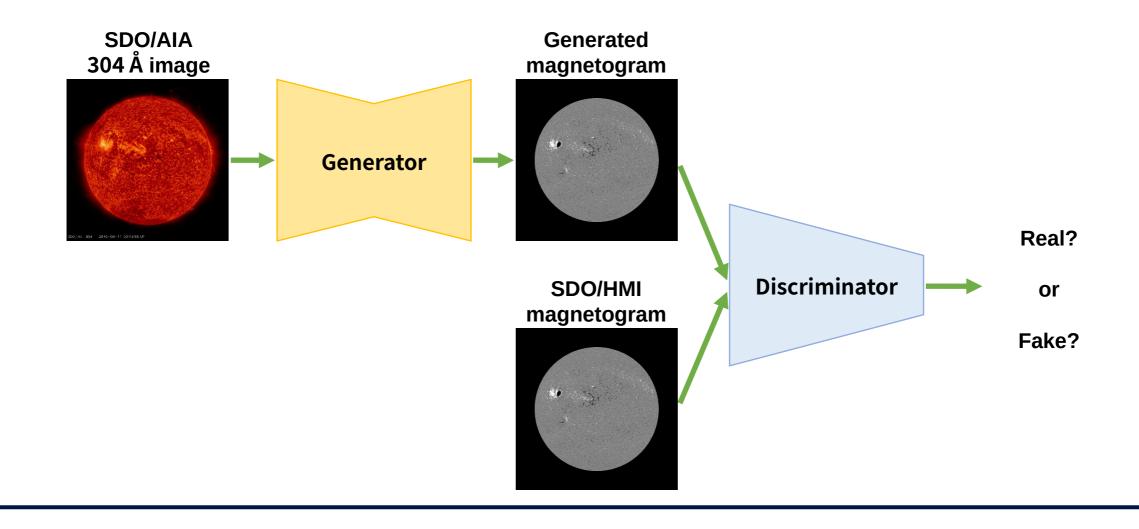


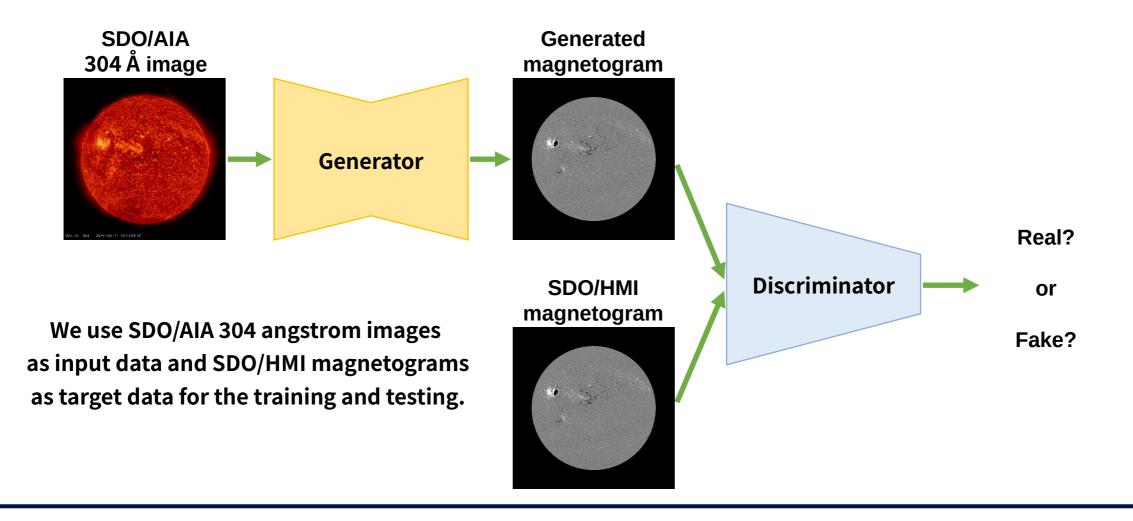
GAN is one of the popular deep learning methods in generation and translation tasks.

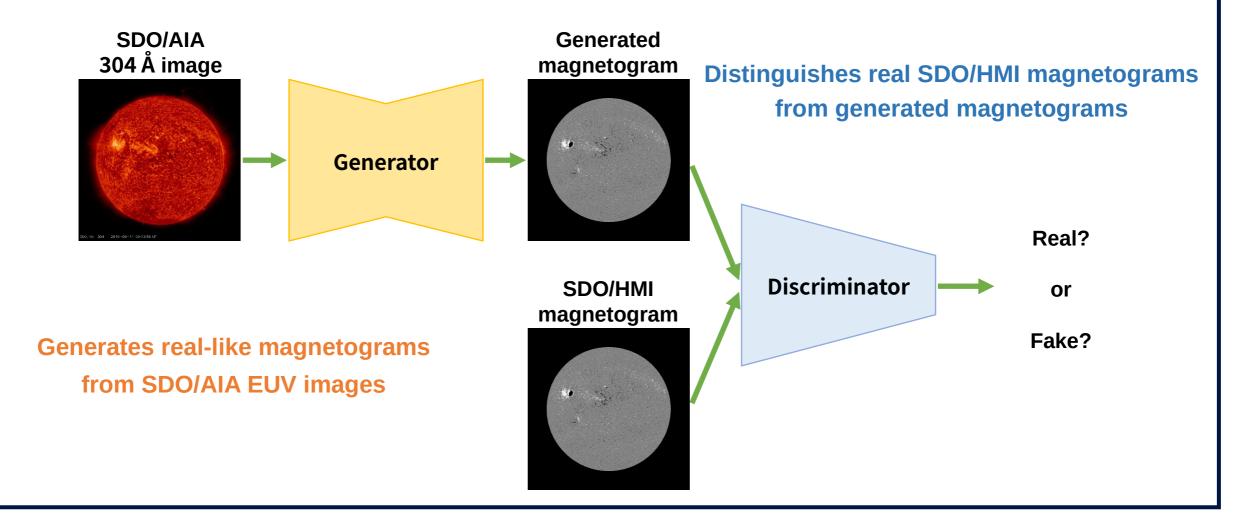


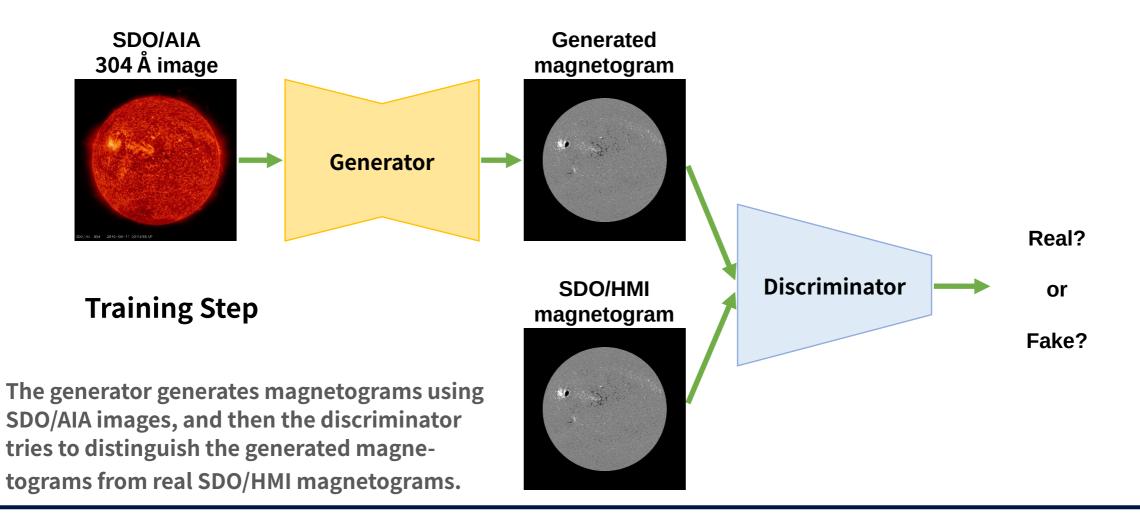


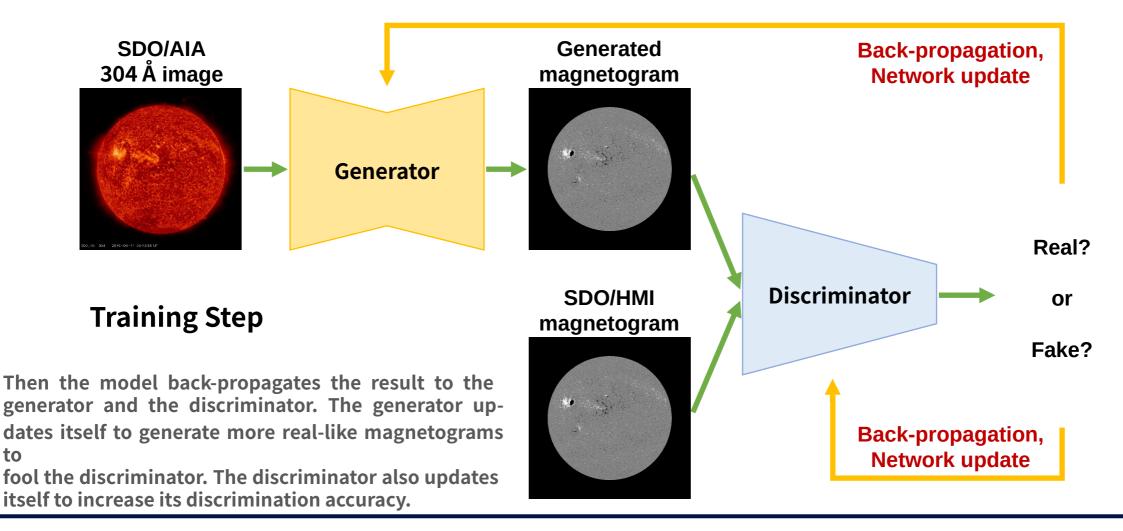
We train the Generator and the Discriminator, this process looks like a competition between the two networks.

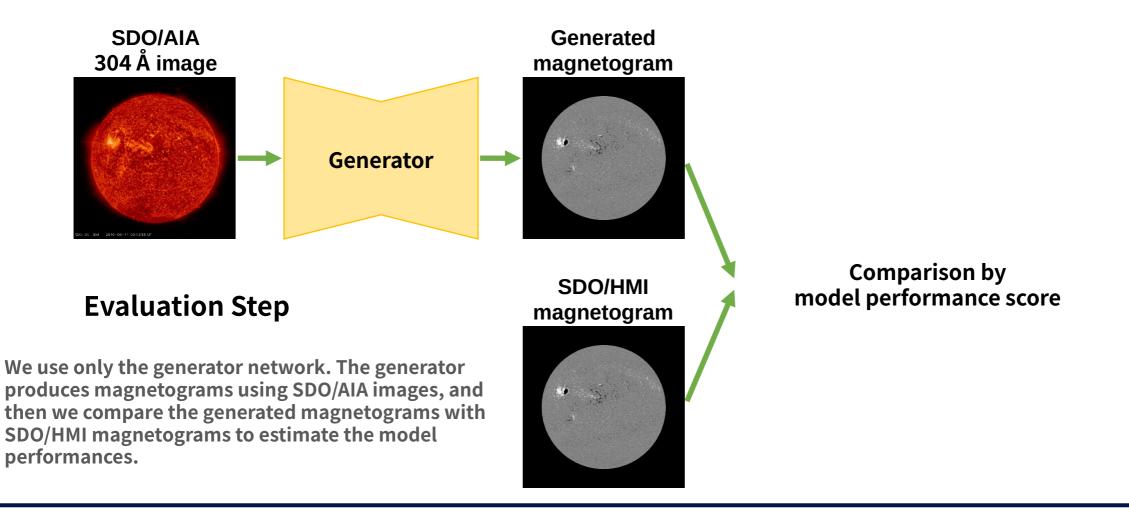




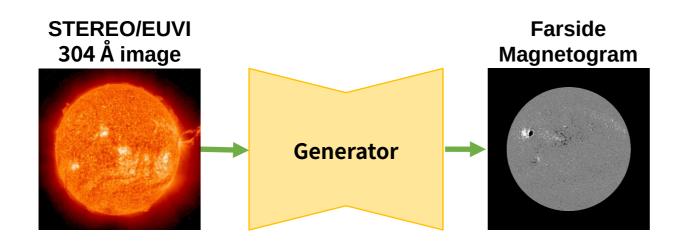




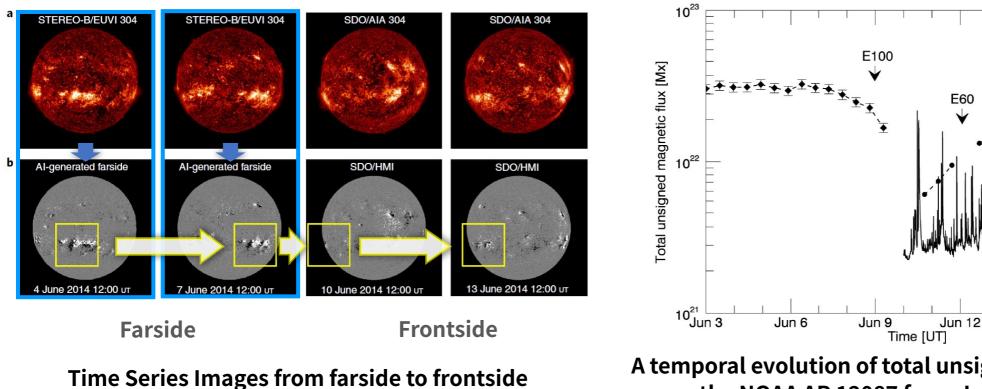




Structure of our model for the translation from solar EUV images to solar magnetograms



Generation Step



A temporal evolution of total unsigned magnetic flux of the NOAA AR 12087 from June 3 to 19 2014

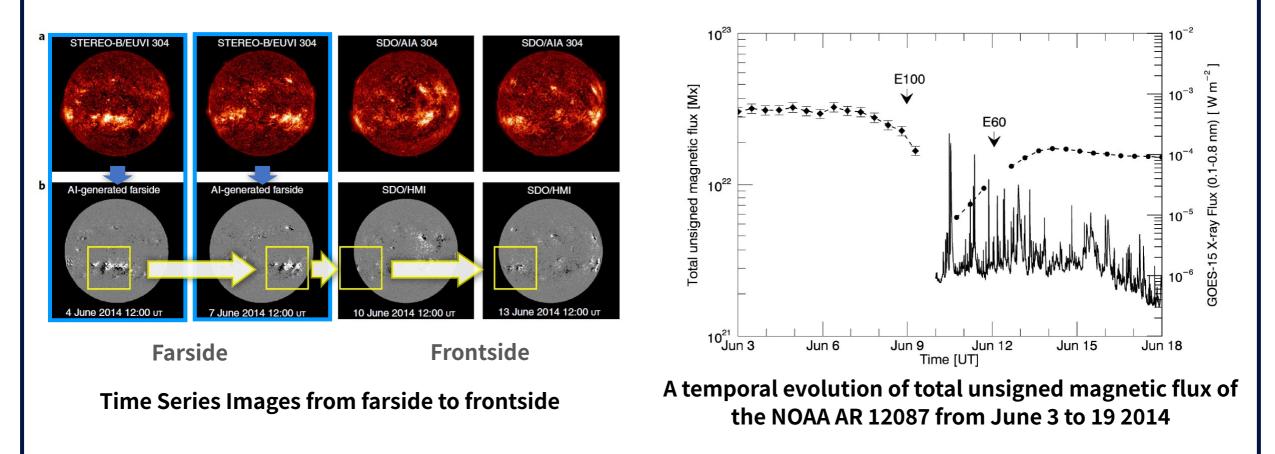
Jun 15

E60

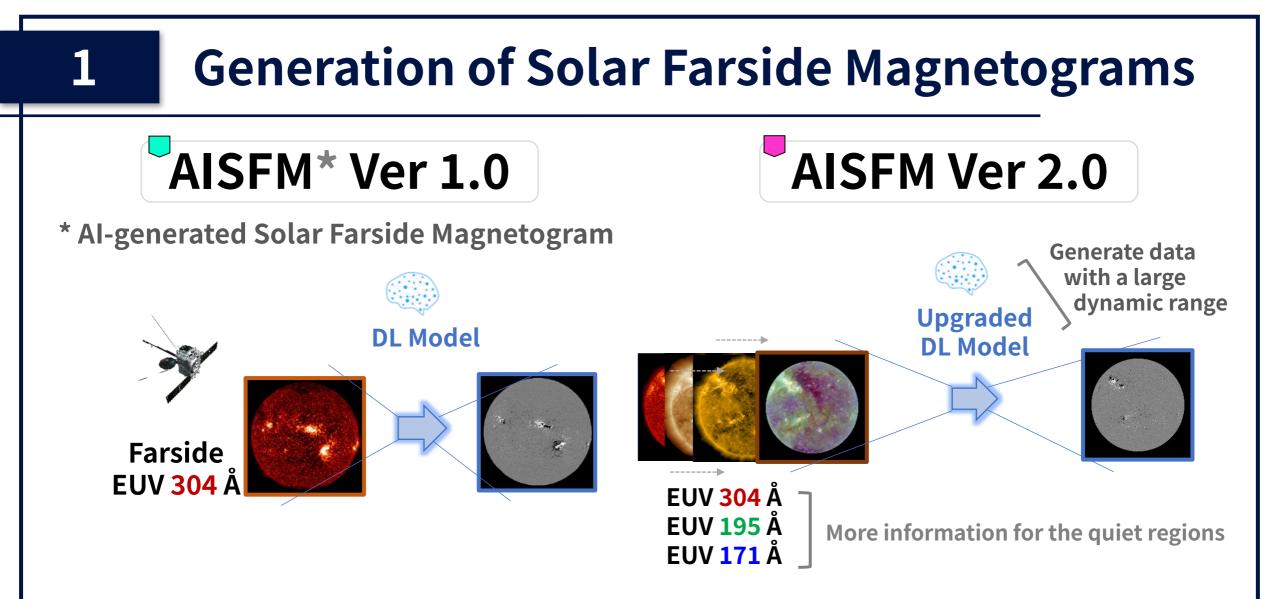
GOES-

Jun 18

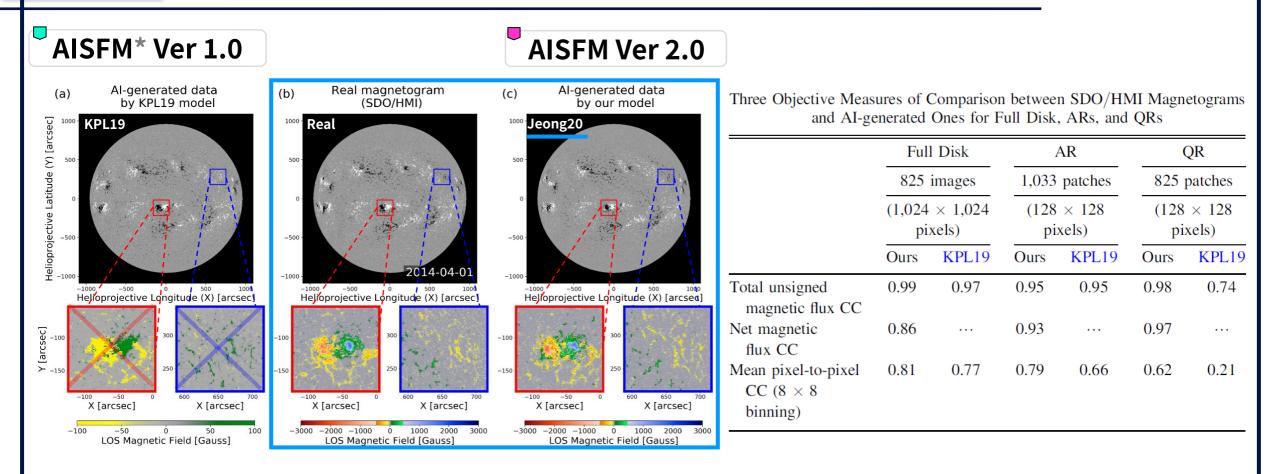
Kim, Park, Lee et al. (2019) suggest a deep learning model for generating solar farside magnetograms from STEREO/EUVI observations. The result shows that we could monitor the temporal evolution of magnetic fields from the solar far side to the solar front side using DL-generated data.



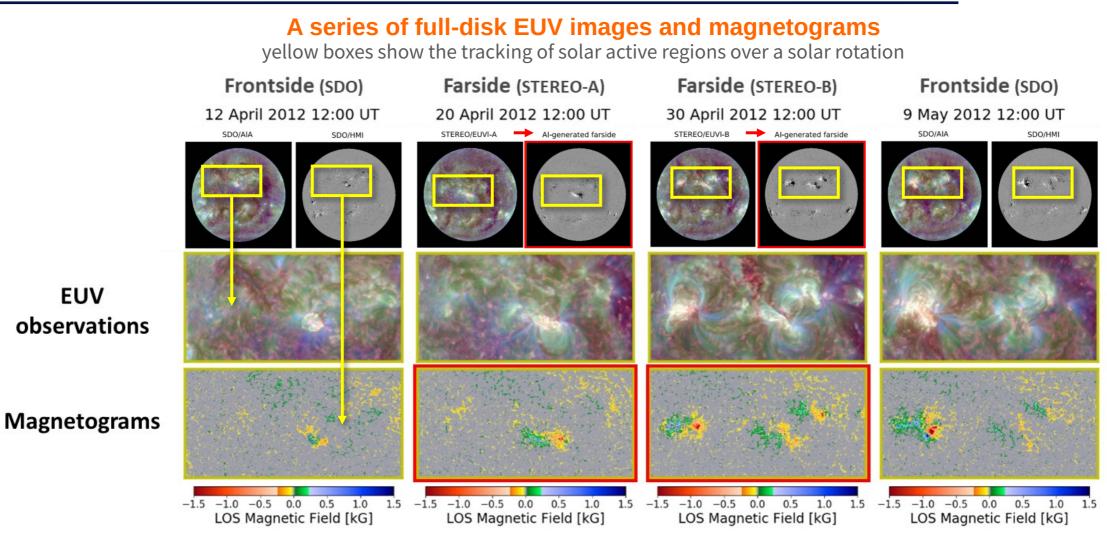
However, this study is limited to the maximum magnetic field strength of 100 G and shows low correlations in solar quiet regions.



Jeong et al. (2020) upgrade the model with 3,000 Gauss dynamic range to generate more realistic magnetic fluxes, and with multi-channel input to improve the generation of quiet regions.



The model (AISFM Ver 2.0) generates both the active and quiet regions more realistically than the previous model (A-ISFM Ver 1.0) and shows better results in quantitative comparisons.

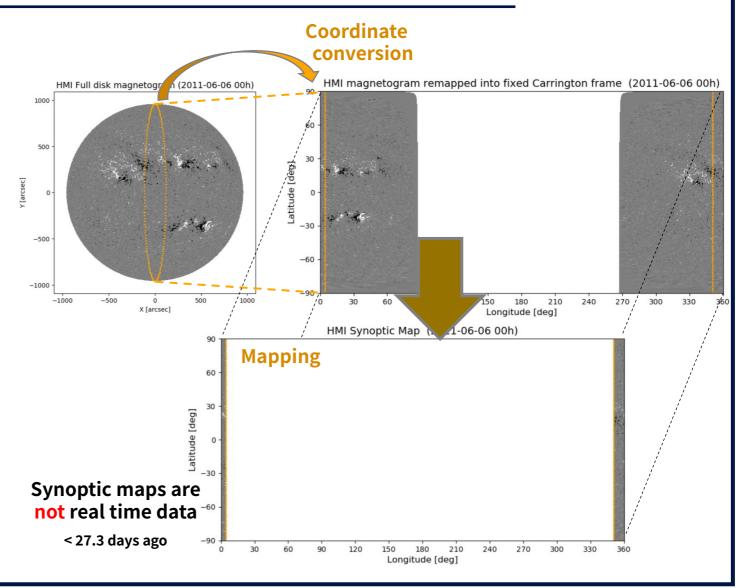


The model generates solar active regions with more realistic magnetic field strengths.

Conventional Synoptic Map

Conventional magnetic field synoptic maps have been constructed by merging frontside magnetograms over a 27 day solar rotation period because there is no magnetogram in solar farside.

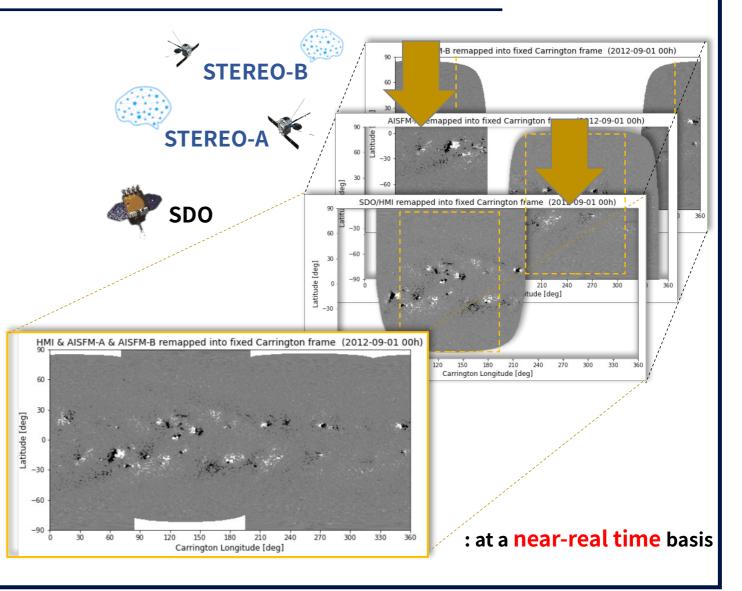
The conventional synoptic maps are not based on real-time ones.

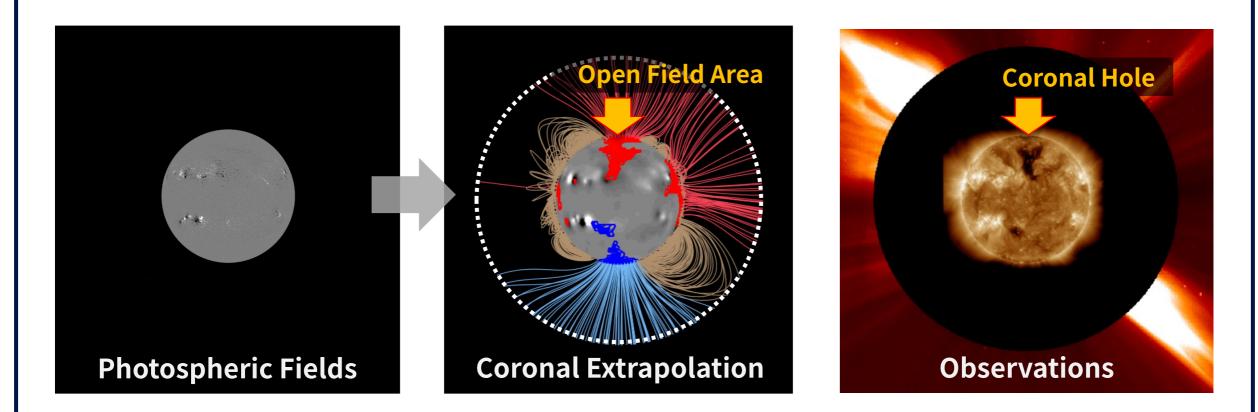


HMI & AI Synchronic Map

We construct AI synchronic global magnetic field maps by merging the farside magnetograms and SDO/HMI magnetograms.

These AI synchronic maps can cover mostly real-time global solar photospheric fields.

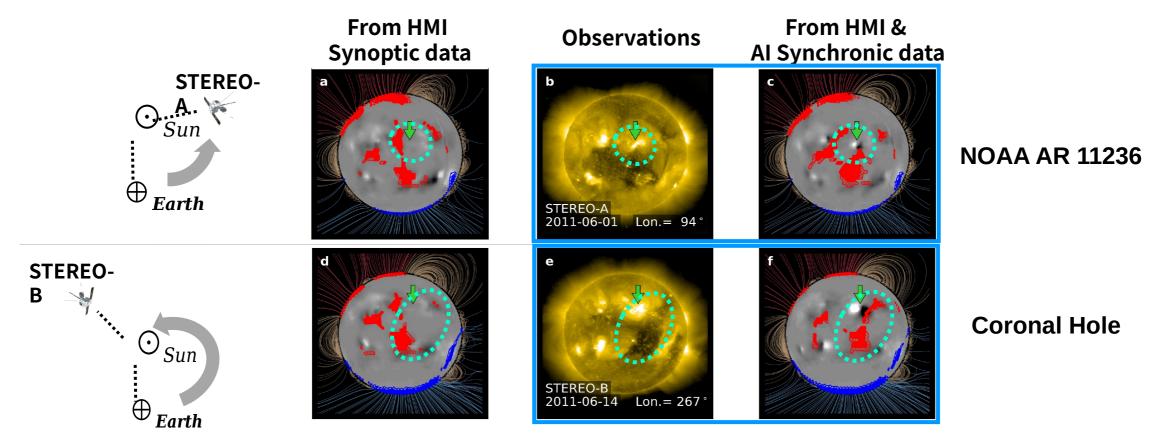




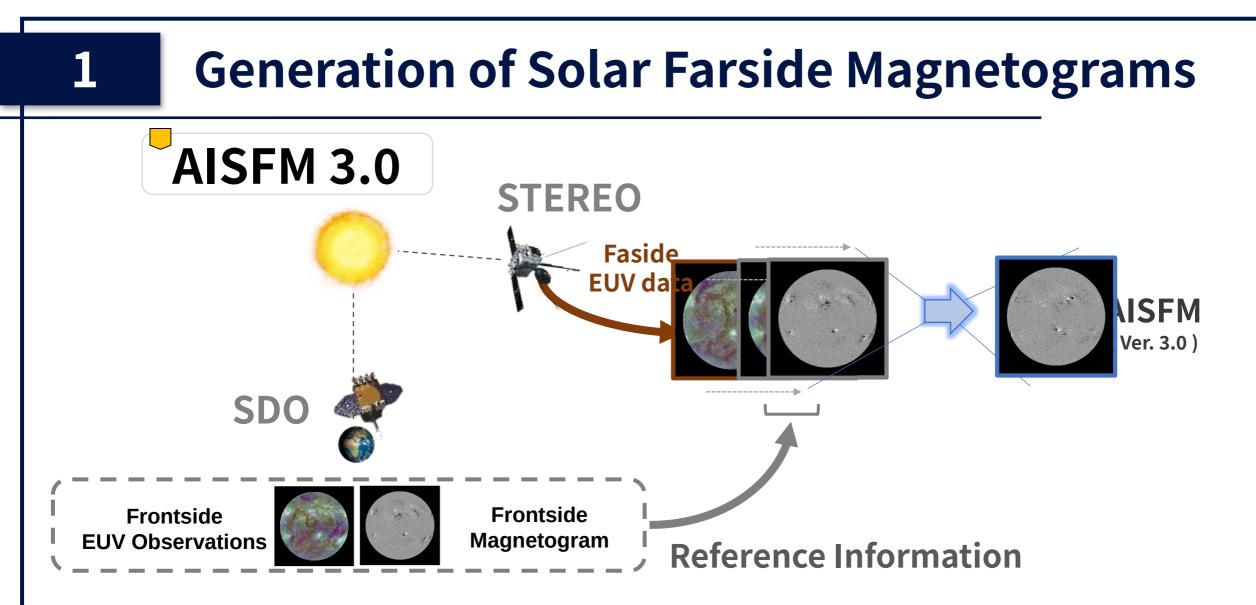
We extrapolate the global coronal magnetic field from the AI synchronic maps using Potential Field Source Surface (PFSS) model, then compare the results with coronal observations.

Open field lines, which are computed by the PFSS model, arriving at the source surface are associated with coronal holes.

Comparison between farside solar EUV observations and results of PFSS extrapolations



The extrapolation results using AI synchronic data well represent the appearance of the active region and the coronal hole, and the results agree with the observations.



We are trying to improve our model by providing solar frontside data to the model as reference information.

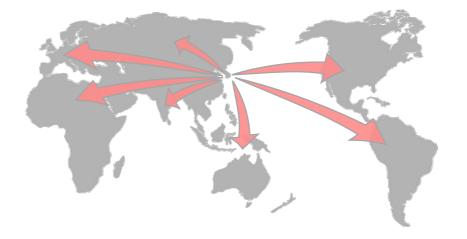
Public release of solar farside magnetograms soon



-A: 2011.01 ~ 2019.12 (~ 47 GB) -B: 2011.01 ~ 2014.09 (~ 21 GB)



We are going to release the solar farside magnetograms and AI synchronic maps through Korean Data Center (KDC) for SDO in Korean Astronomy and Space Science Institute (KASI).





KDC for SDO in KASI

De-noising SDO/HMI Magnetograms

Park et al., 2020

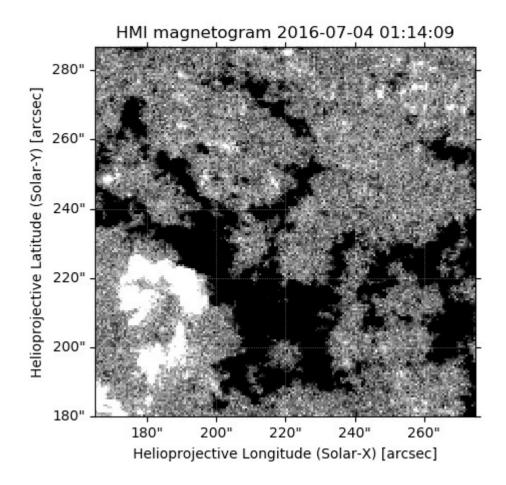
Denoising SDO/HMI Magnetogram

Liu+ (2012) reported that

"An upper bound to the random noise for the 1" res-

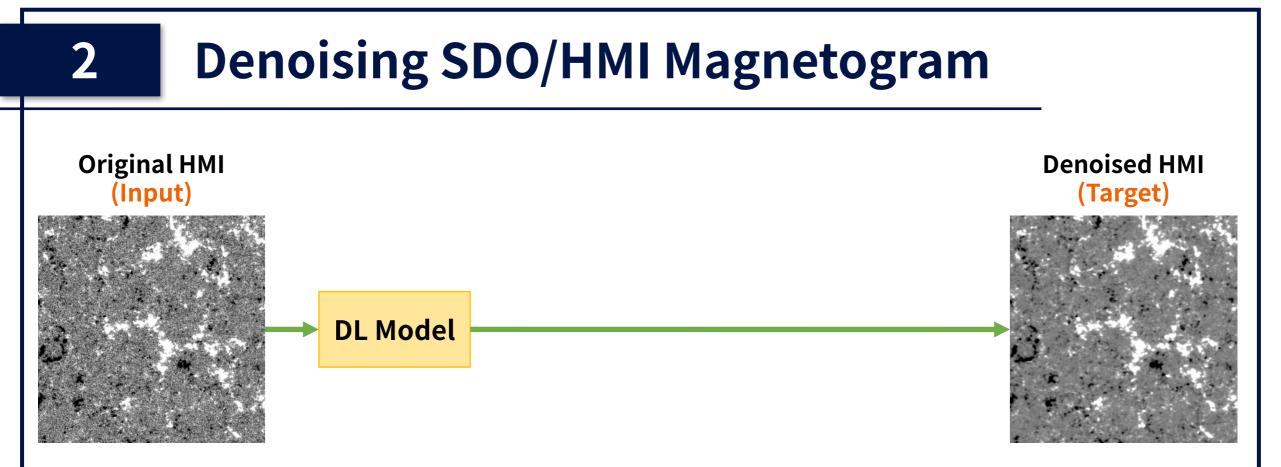
olution HMI 45-second magnetograms is 10.2 G, and

6.3 G for the 720-second magnetograms."



2 Denoising SDO/HMI Magnetogram

- Several studies investigated weak solar magnetic field structures such as solar intranetwork and small bi-poles by integrating magnetic field observations to increase the signal-to-noise ratio (Wang et al. 1995; Schrijver et al. 1997; Chae et al. 2001).
- Several studies tried to reduce the noise level of solar magnetograms by several types of computing algorithms (DeForest 2017; DiasBaso et al. 2019).
- In this study, we apply two deep learning methods to denoising SDO/HMI magnetograms.



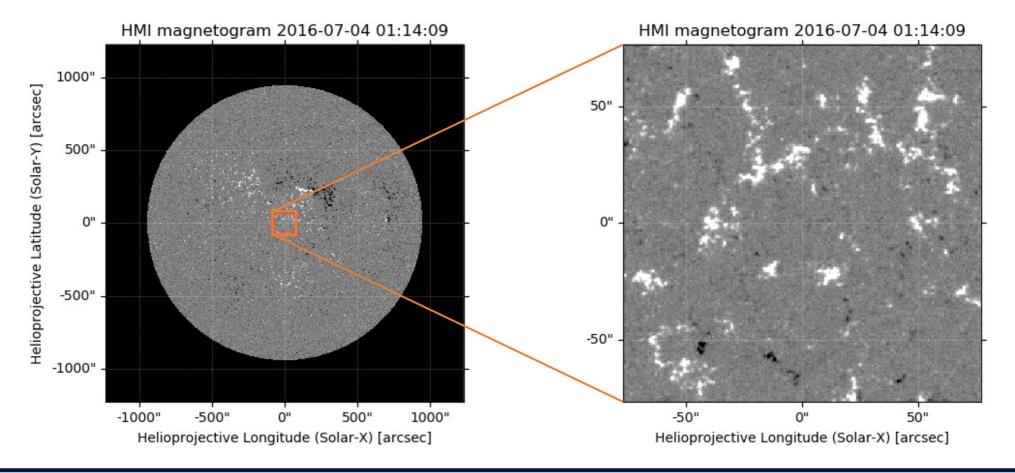
We design a deep learning model that translates from original magnetograms to corresponding denoised magnetograms.

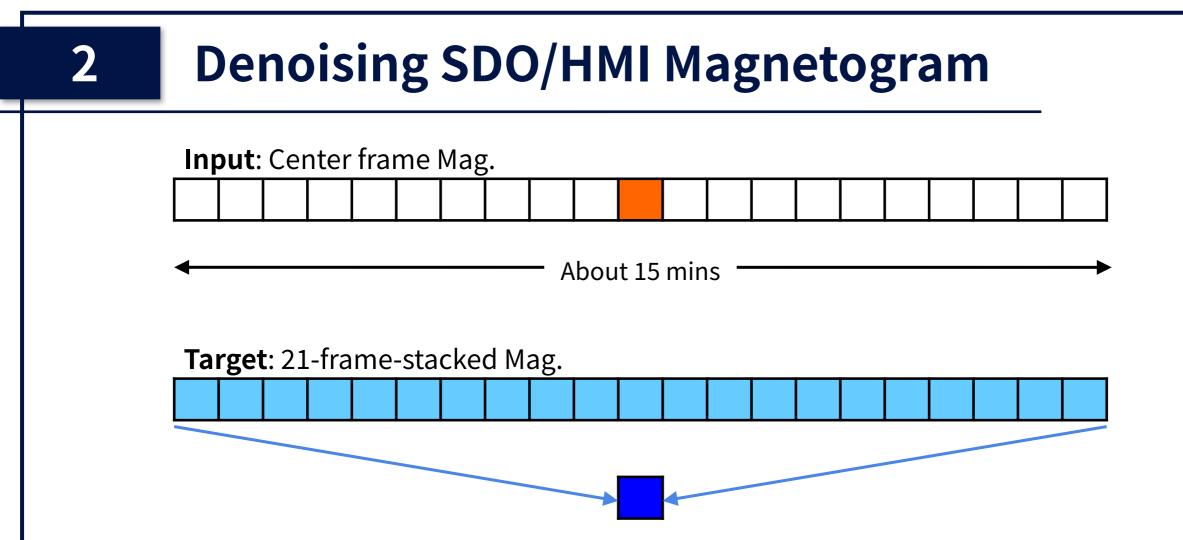
-> We need pairs of the original magnetograms and the denoised magnetograms to train the model.

2 Denoising SDO/HMI Magnetogram

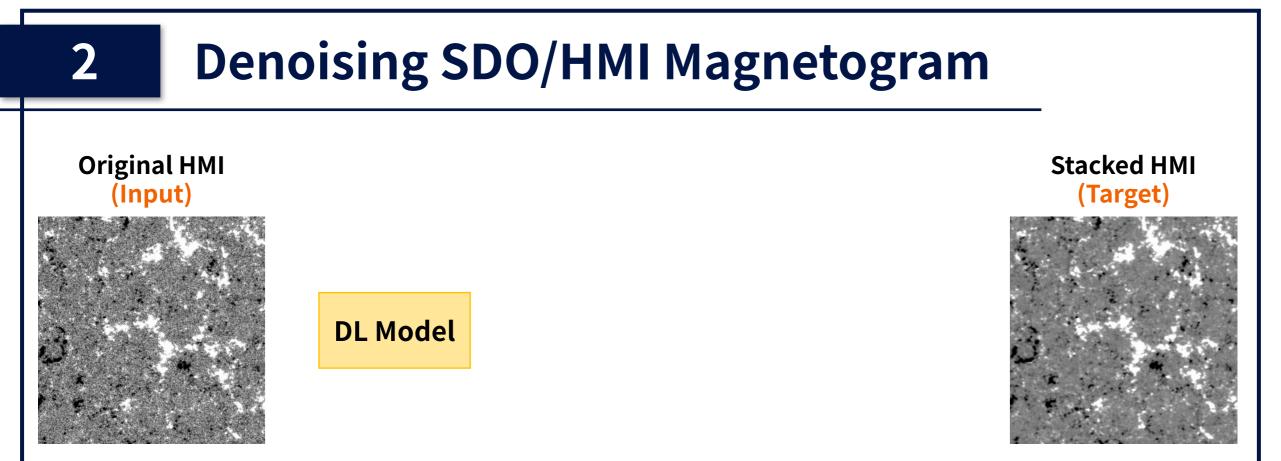
Crop patches from full disk HMI 45-second magnetogram

patch size: 256 x 256 (± 76.8 arcsec)

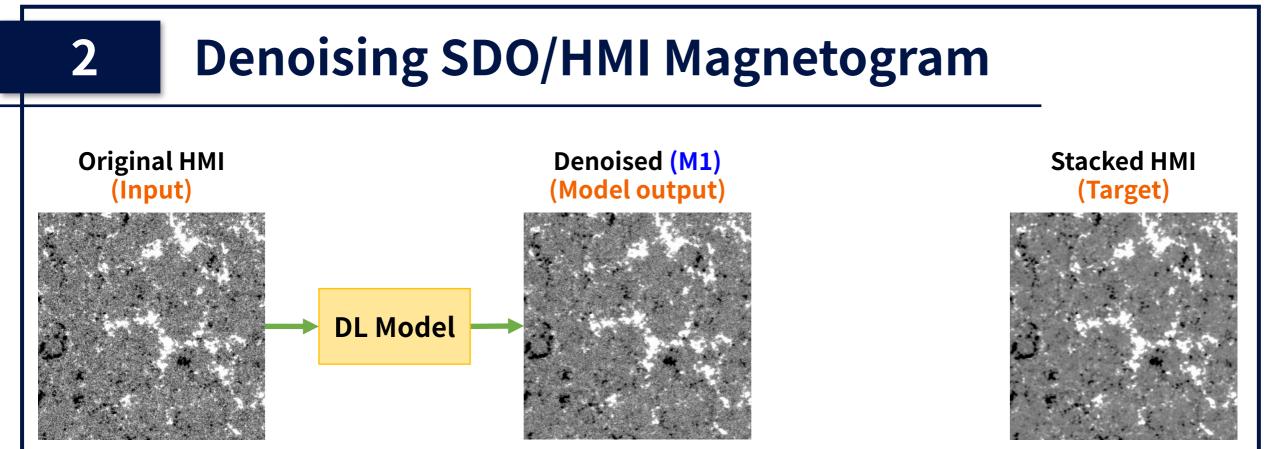




We integrate 21 magnetogram patches that include 10 frames before and 10 frames after the input magnetogram patch considering solar rotation. A stacked magnetogram has approximately 15 minutes of exposure time.

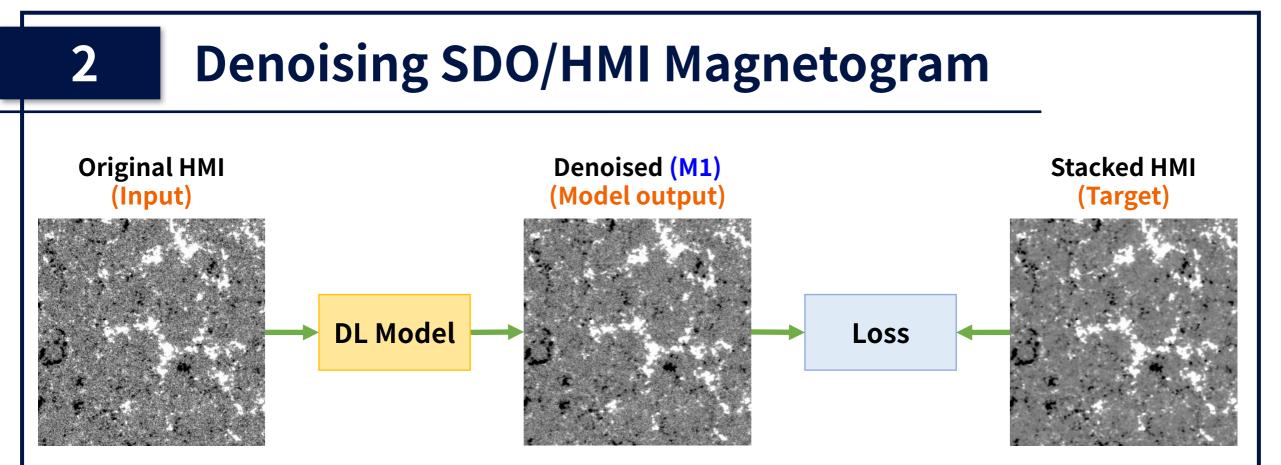


We prepare the pairs of the original magnetograms and the stacked magnetograms.



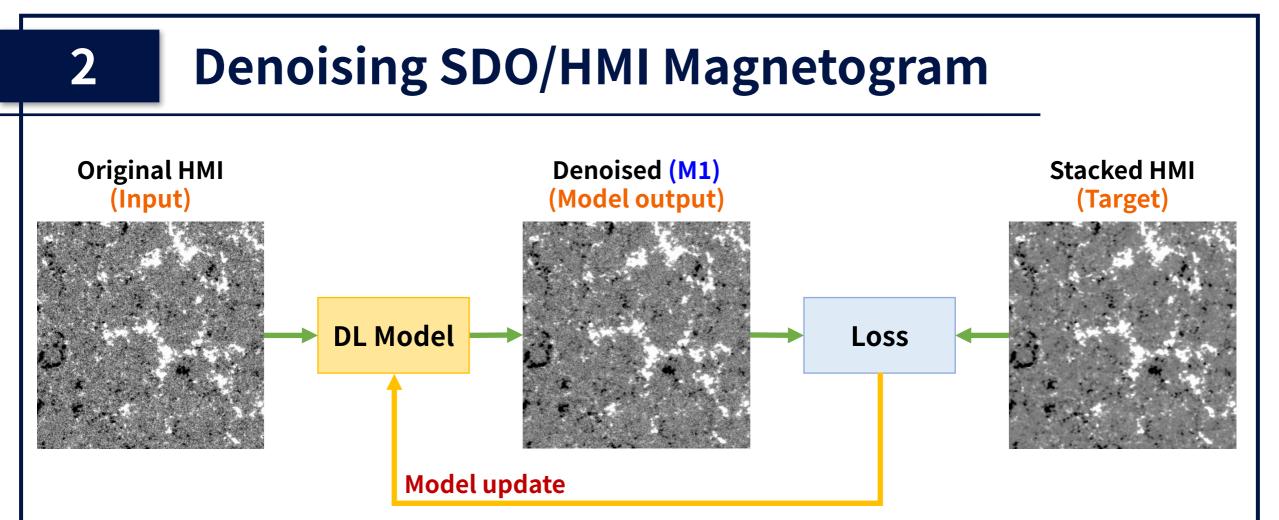
We prepare the pairs of the original magnetograms and the stacked magnetograms. The model

1) generates the denoised magnetograms using the original magnetograms,



We prepare the pairs of the original magnetograms and the stacked magnetograms. The model

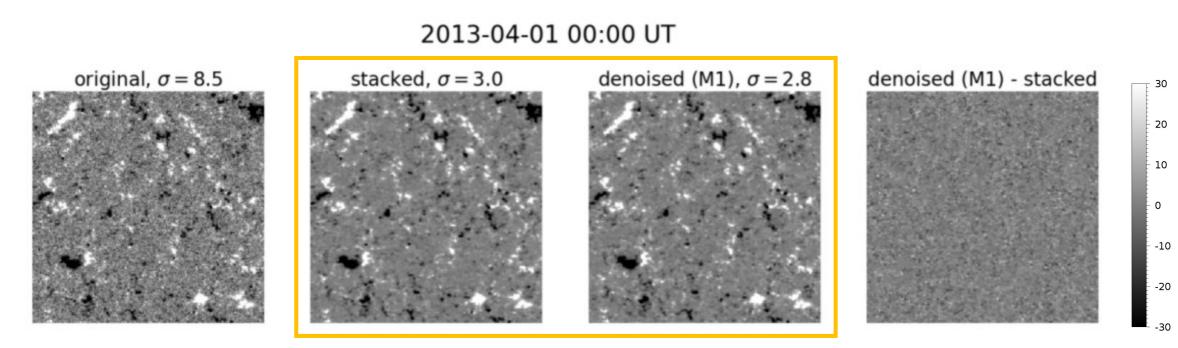
- 1) generates the denoised magnetograms using the original magnetograms,
- 2) calculates the difference between the denoised and the stacked magnetograms,



We prepare the pairs of the original magnetograms and the stacked magnetograms. The model

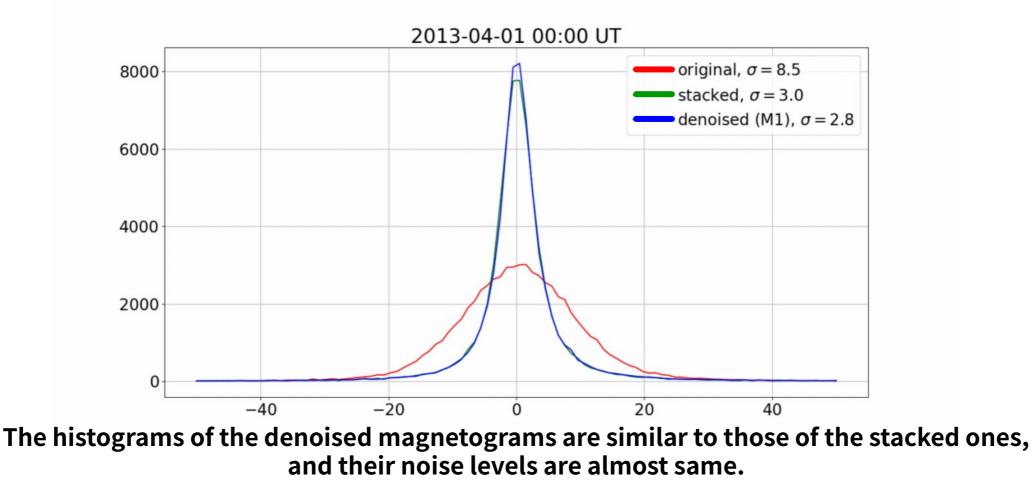
- 1) generates the denoised magnetograms using the original magnetograms,
- 2) calculates the difference between the denoised and the stacked magnetograms,
- 3) back-propagates the difference, and updates itself to minimize the difference.

Comparisons between the original, stacked, and denoised magnetograms



The denoised magnetograms by our model are consistent with the stacked ones.

Histograms of magnetic flux densities from the original, stacked, and denoised magnetograms

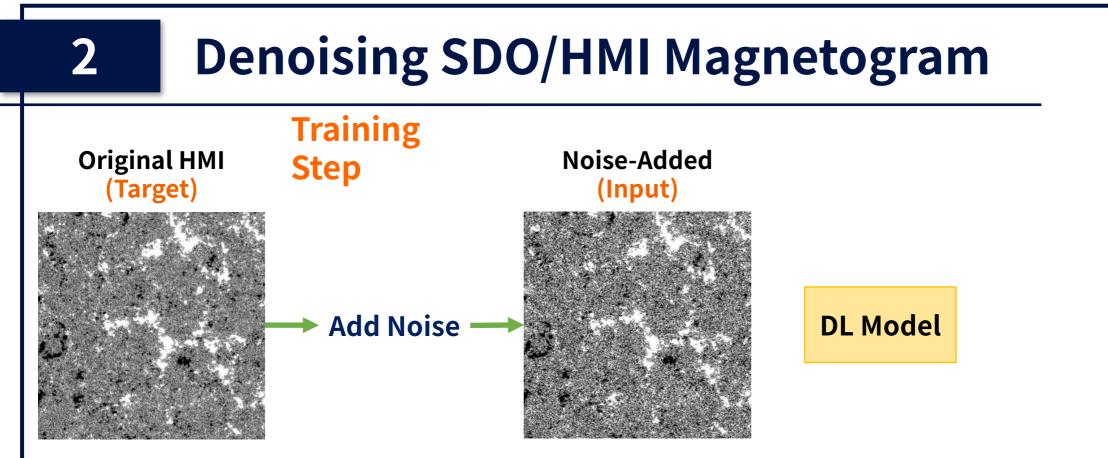


- Our model based on image translation method successfully reduce the noise level of SDO/HMI magnetograms.
- This method can be applied only when we have pairs of the original magnetograms (input) and the denoised magnetograms (target).
- The quality of the model outputs can be affected by the condition of the target data, such as the number of frames for the stacked magnetograms.

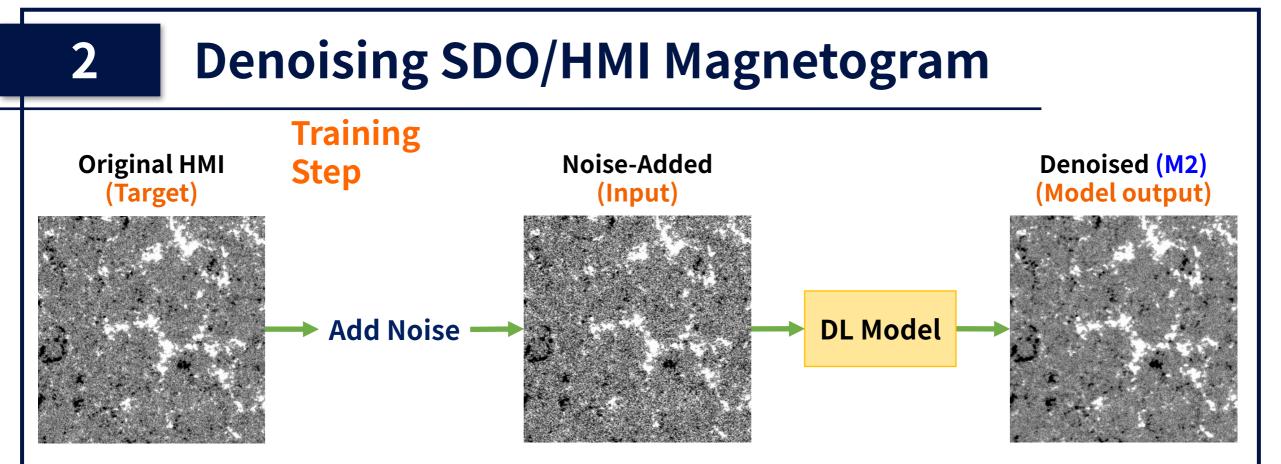
- Our model based on image translation method successfully reduce the noise level of SDO/HMI magnetograms.
- This method can be applied only when we have pairs of the original magnetograms (input) and the denoised magnetograms (target).
- The quality of the model outputs can be affected by the condition of the target data, such as the number of frames for the stacked magnetograms.
- We design an additional model (M2) based on AutoEncoder method that can train without target magnetograms.



The dataset is the same as the previous study, but we will not use the stacked magnetograms.

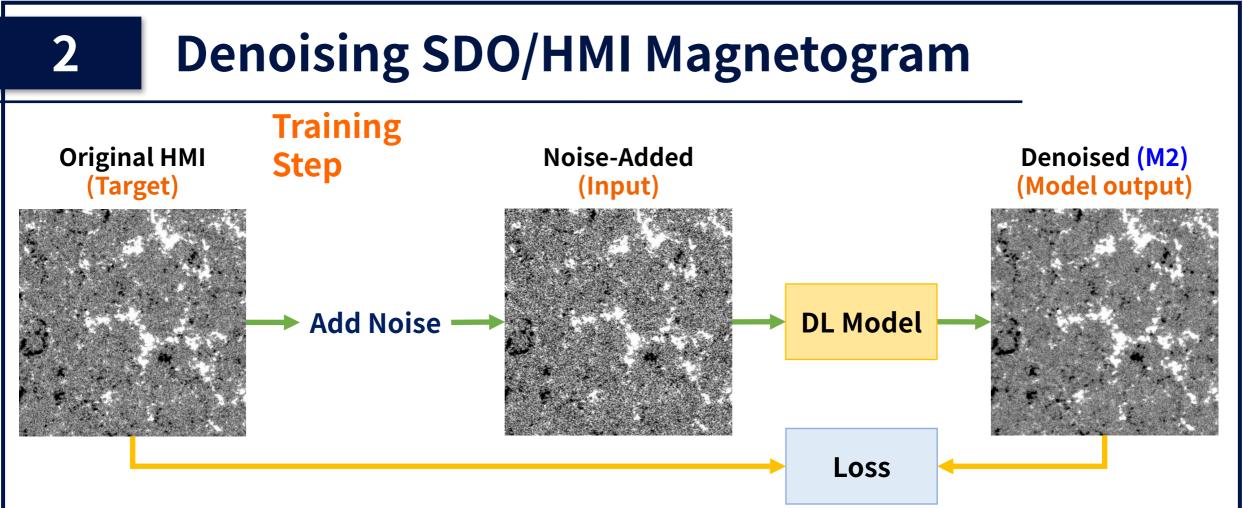


We prepare the original magnetograms and add random Gaussian noise to the magnetograms. The noise distributions are similar to those of the original ones.



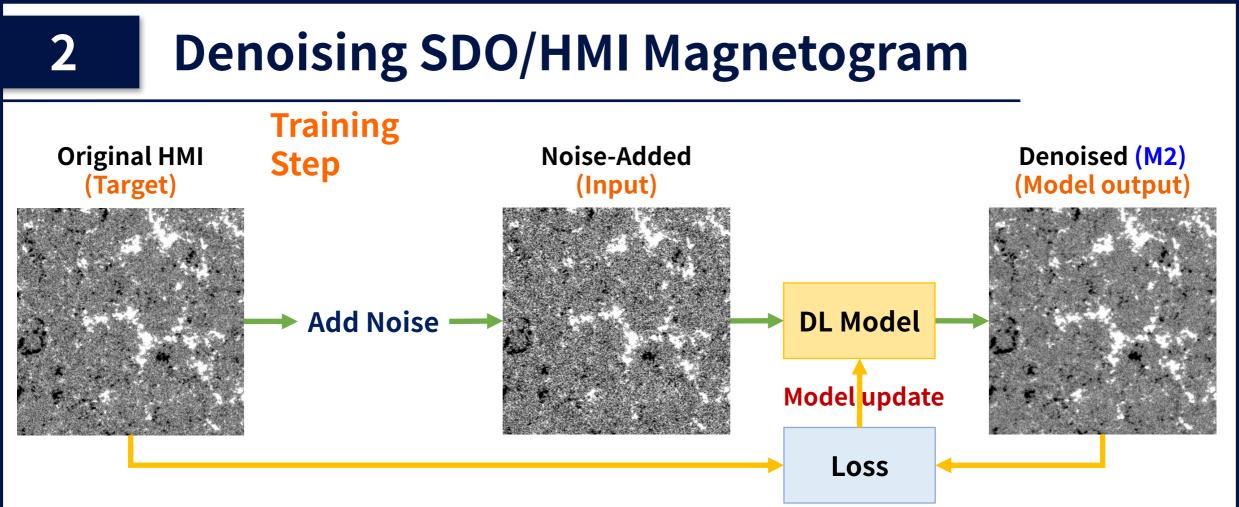
We prepare the original magnetograms and add random Gaussian noise to the magnetograms. The model

1) generates the denoised magnetograms using the noise-added magnetograms,



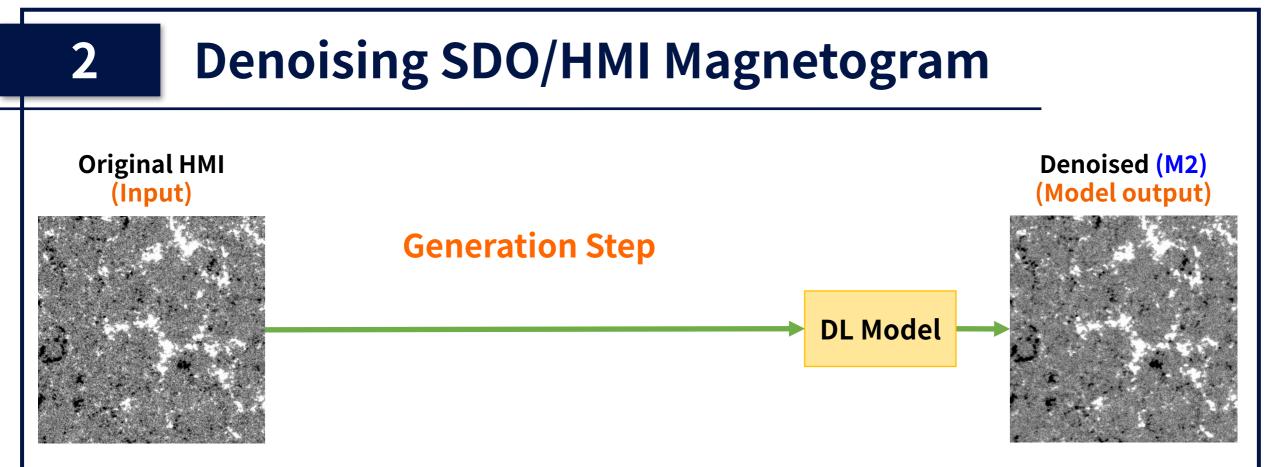
We prepare the original magnetograms and add random Gaussian noise to the magnetograms. The model

- 1) generates the denoised magnetograms using the noise-added magnetograms,
- 2) calculates the difference between the denoised and the original magnetograms,



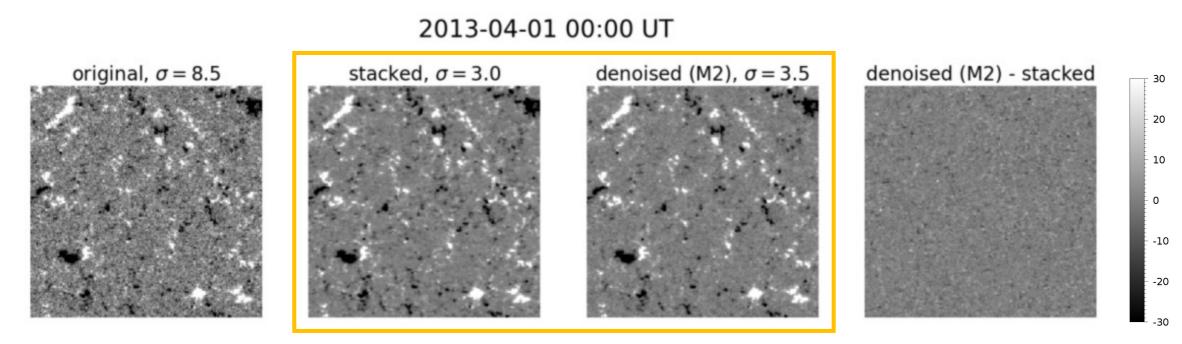
We prepare the original magnetograms and add random Gaussian noise to the magnetograms. The model

- 1) generates the denoised magnetograms using the noise-added magnetograms,
- 2) calculates the difference between the denoised and the original magnetograms,
- 3) back-propagates the difference, and updates itself to minimize the difference.



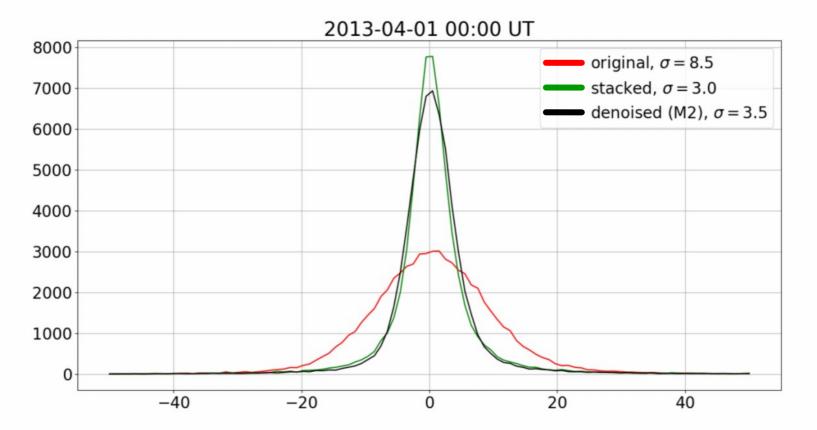
The model generates the denoised magnetograms using the original magnetograms.

Comparisons between the original, stacked, and denoised magnetograms



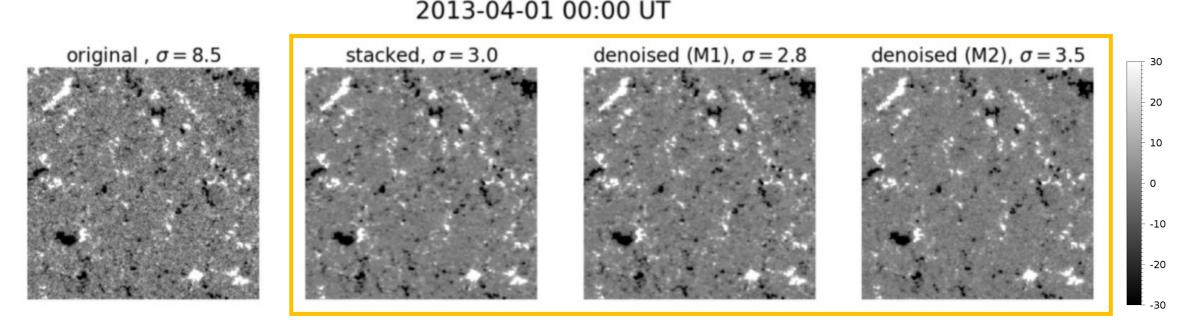
The denoised magnetograms by our AutoEncoder model are consistent with the stacked ones

Histograms of magnetic flux densities from the original, stacked, and denoised magnetograms



The histograms of the denoised magnetograms are similar to those of the stacked ones

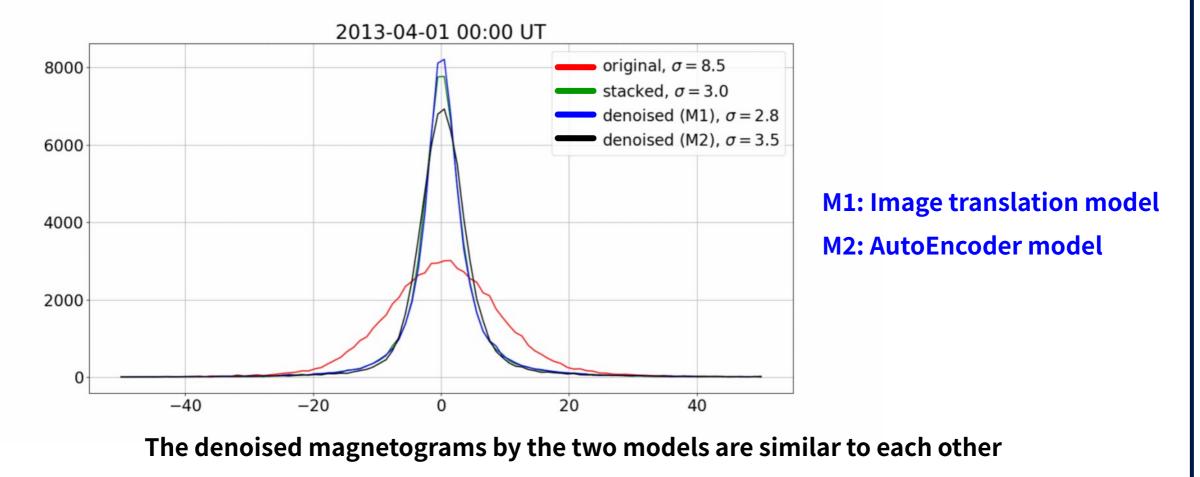
Comparisons between original, stacked, and denoised magnetograms by two models



The denoised magnetograms by two models are consistent with each other.

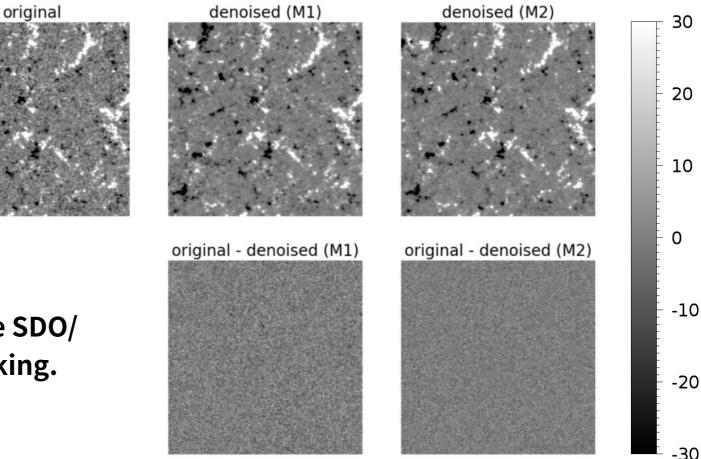
M1: Image translation model, M2: AutoEncoder model

Histograms of magnetic flux densities from the original, stacked, and denoised magnetograms by two models



Application of our models to 21 frames of original SDO/HMI magneotgrams

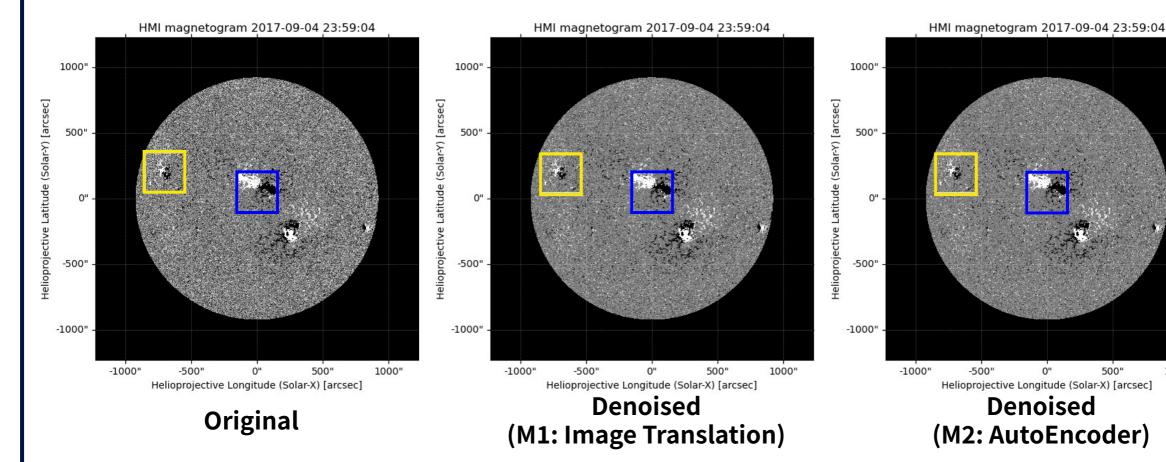
2013-04-15 22:00 UT



M1: Image translation model M2: AutoEncoder model

After the training, we can denoise SDO/ HMI magnetograms without stacking.

Application of our model to a full-disk SDO/HMI magnetogram

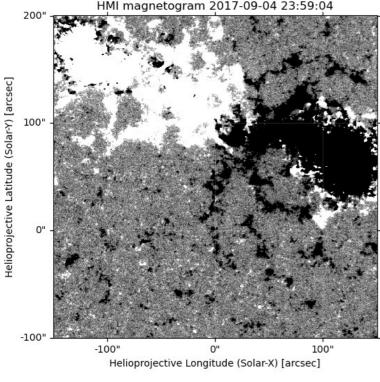


0"

500"

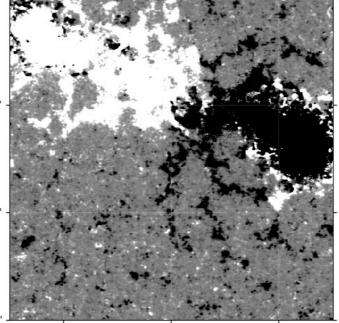
1000"

Application of our model to a full-disk SDO/HMI magnetogram: center of disk

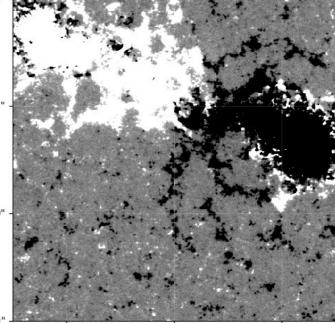


Original, noise level: 9.1 G

HMI magnetogram 2017-09-04 23:59:04

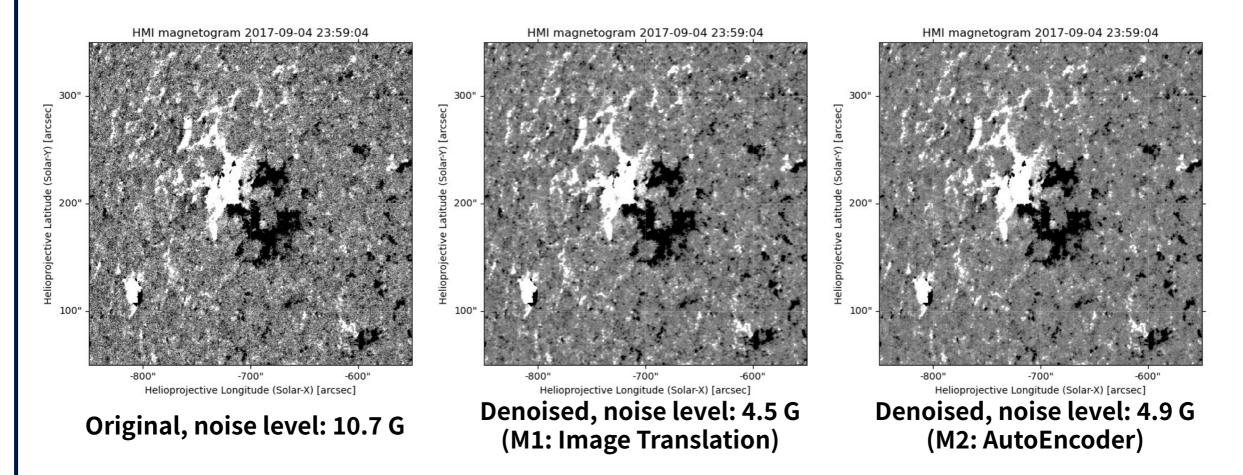


-100" 0" 100" Helioprojective Longitude (Solar-X) [arcsec] Denoised, noise level: 3.4 G (M1: Image Translation) HMI magnetogram 2017-09-04 23:59:04



-100" 0" 100" Helioprojective Longitude (Solar-X) [arcsec] Denoised, noise level: 3.9 G (M2: AutoEncoder)

Application of our model to a full-disk SDO/HMI magnetogram: near the limb

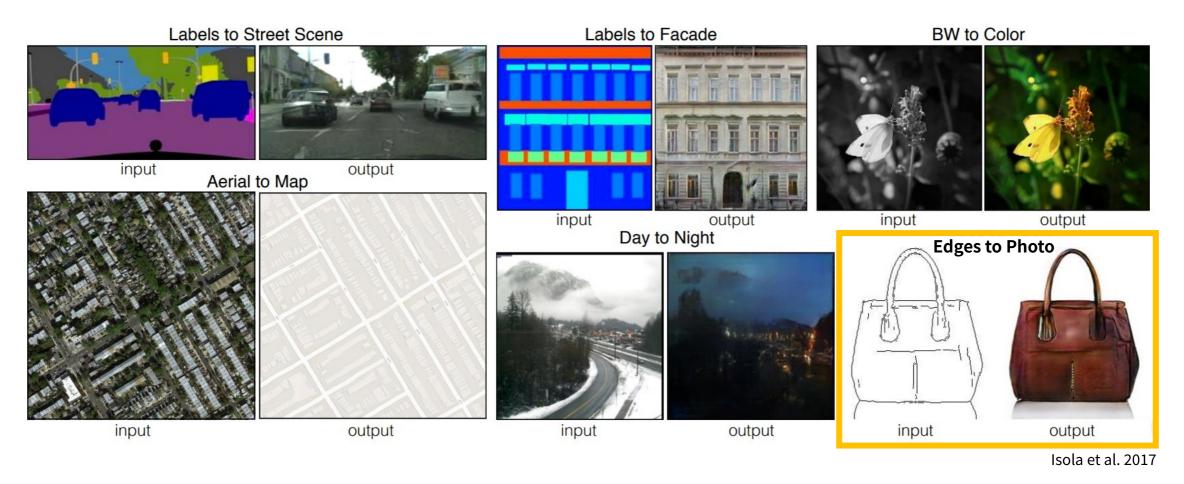


- The image-translation method can be applied to denoising solar and space weather data if we can build many target noise-reduced data.
- If it is difficult to build the denoised target data, the AutoEncoder method can be applied to denoising solar and space weather data as an alternative.

Generation of Modern Satellite Images from Galileo sunspot drawings in 1612

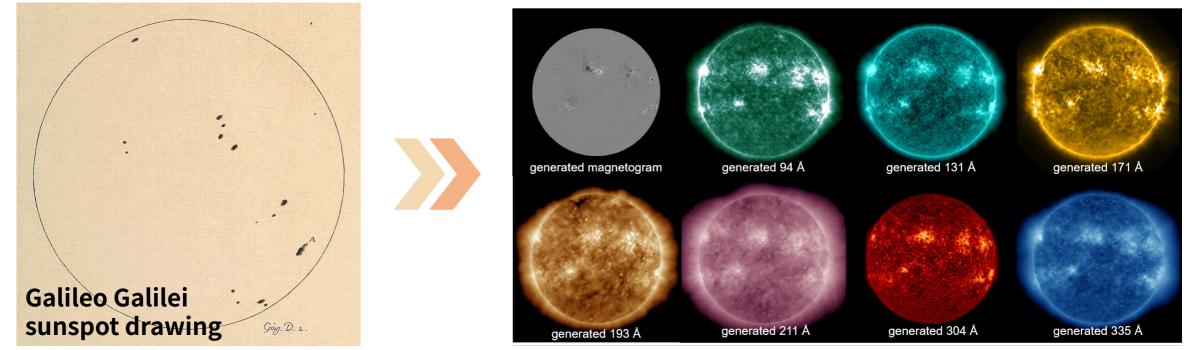
Lee et al., 2021

3 Generation of Satellite Image from Galileo Sunspot



We have similar data to this example, that is sunspot drawings.

3 Generation of Satellite Image from Galileo Sunspot



http://galileo.rice.edu/sci/observations/sunspot_drawings.html

poster session

Title: Generation of Modern Satellite Data from Galileo Sunspot Drawings by Deep Learn-

ing

Author: Harim Lee

THANK YOU

