







# Towards Lucky Imaging for Quiet-Time Low-Frequency Radio Solar Observations

Kamen Kozarev<sup>1</sup> (kkozarev@astro.bas.bg), Peijin Zhang<sup>1</sup>, Pietro Zucca<sup>2</sup>, Oleg Stepanyuk<sup>1</sup>, Mohamed Nedal<sup>1</sup> <sup>1</sup> Institute of Astronomy, Bulgarian Academy of Sciences <sup>2</sup> ASTRON, The Netherlands Institute of Radio Astronomy

#### Introduction

- Low-frequency interferometric radio imaging observations (20-250 MHz) of the quiet Sun important for understanding corona
- Also important for studying the young solar wind and dim non-burst activity too dim to be observed in spectral data.
- Such observations rarely reported in the literature, because of
  - relative scarcity of observations;
  - difficulty to obtain high quality processed images.
- Daytime ionosphere severely impacts imaging observations and reduces quality, especially when imaging extended corona.
- To mitigate the effects of the ionosphere, exploring machine learning techniques to enable automated snapshot lucky imaging.
- We outline our approach for using ML to select images of sufficient quality, and present initial results.

## Methodology - Data

- LOFAR solar data for 4 hours of quiet-time observations on 08/04/2017 were calibrated (baseline visibility phases and amplitudes) using standard LOFAR software DP3;
- Result is a Measurement Set (see tutorial on MS here: <u>https://www.youtube.com/watch?v=lwgleKRqfws</u>)
- 253 baselines and 50k+ samples (~4 hours at 0.25s per sample)
- Extract baseline visibility magnitudes:







### Methodology - K-Means Clustering

- Extremely high visibility magnitudes are taken as a sign of corrupted observations (due to bad calibration, ionospheric interference, etc.)
- To remove such baselines, perform K-Means clustering of the visibility amplitudes for each observing interval/sample of duration 0.25 seconds in the solar measurement set.
- The clustering provides self-consistently limiting value of the visibility magnitude.
- We evaluate the K-parameter, reaching a conclusion that 5 is optimal.
- The selection: the maximum visibility magnitude in the second cluster for each interval/sample.





### **K-Means Clustering - Results**

- Clustering reduces significantly the maximum visibility magnitudes (right plot)
- All baseline points below cut-off are flagged to not use.
- This is done sequentially for all intervals (57520 in our observing dataset).
- Finally, interferometric imaging (CLEANing) is performed on the flagged data.





#### PRELIMINARY RESULTS

- Original images (pre-flagging, left) are compared with the flagged version (right).
- Conclusion: We find a visible improvement of the appearance of the solar signal, especially spatial resolution due to reduced smearing of signal.
- Next steps:
  - Apply technique to snapshot imaging;
  - Apply quality filters also in image domain;
  - Combine images for 'Lucky Imaging' of faint emission.

