

Dynamic Tomographic Estimation of Global Exospheric Hydrogen Density and its Response to a Geomagnetic Storm

Gonzalo Cucho-Padin*, Lara Waldrop

ECE Department, Remote Sensing and Space Sciences Group

University of Illinois at Urbana-Champaign.

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gac3@illinois.edu



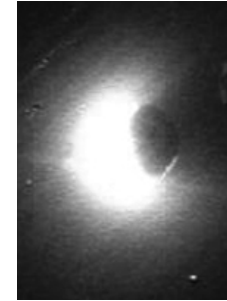
Everyone is a genius. But if you judge a fish by its ability to climb a tree, it will live its whole life believing that it is stupid.

- Albert Einstein

Knowledge of exospheric H density is important but conventional estimation techniques are limited.

What is the topic of study?

- ⊙ Atomic hydrogen (H) located at the outermost layer of the Earth's atmosphere, resonantly scatters solar Lyman-alpha (121.6nm) radiation



[1]

Why do we need to study this topic?

- ⊙ To understand various solar-terrestrial interactions such as ring current decaying rate, plasmaspheric refilling as well as evaluate the permanent H escape.



[2], [3]

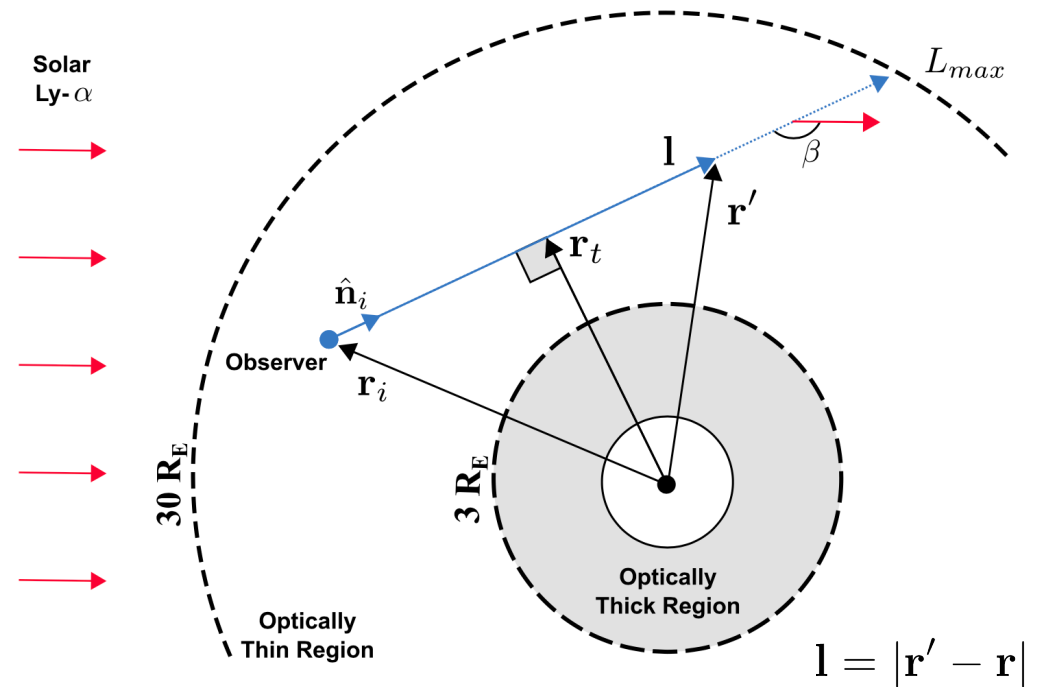
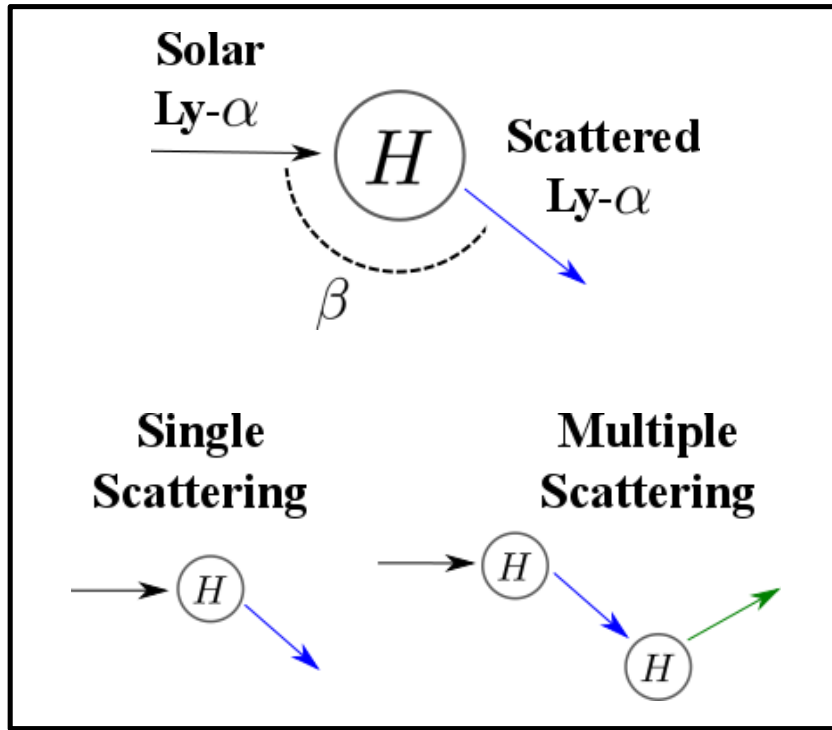
How can we measure the H density?

- ⊙ Direct (in situ) sensing vs. remote sensing.

Image sources: [1] NASA Apollo 16 Mission,
[2] <https://commons.wikimedia.org/wiki/File:AncientMars.jpg> ,
[3] <http://pics-about-space.com/>

Main Goal: Generate a remote sensing technique to estimate the Time-dependent, 3-D Hydrogen density distribution in the exosphere.

Hydrogen density estimation leverages the linearity of the optically thin emission model ($>3R_E$)



emission intensity (measured) [R] \rightarrow $I(\mathbf{r}, \hat{\mathbf{n}}, t)$

LAD/TWINS \rightarrow $I(\mathbf{r}, \hat{\mathbf{n}}, t)$

Ly-alpha resonant scattering rate (measured) [photons.s⁻¹] \rightarrow $g^*(t)$

SEE/TIMED \rightarrow $g^*(t)$

emitter H density (unknown) [cm⁻³] \rightarrow $n_H(l)$

scattering phase function (known) \rightarrow $\Psi(\beta)$

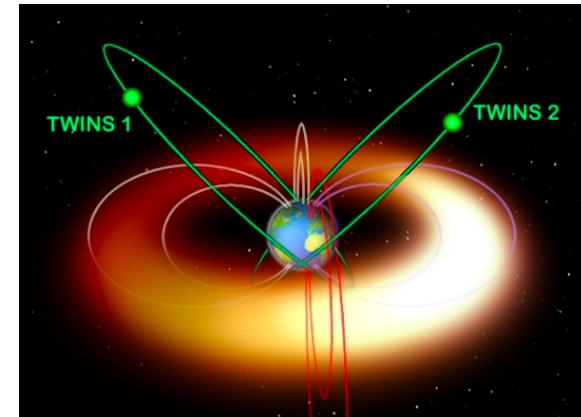
interplanetary Background (measured) [R] \rightarrow $I_{IP}(\hat{\mathbf{n}}, t)$

SOHO/SWAN \rightarrow $I_{IP}(\hat{\mathbf{n}}, t)$

$$I(\mathbf{r}, \hat{\mathbf{n}}, t) = \frac{g^*(t)}{10^6} \int_0^{L_{max}} n_H(l) \Psi(\beta) dl + I_{IP}(\hat{\mathbf{n}}, t)$$

Example of technique feasibility using the NASA's TWINS mission data (static reconstruction)

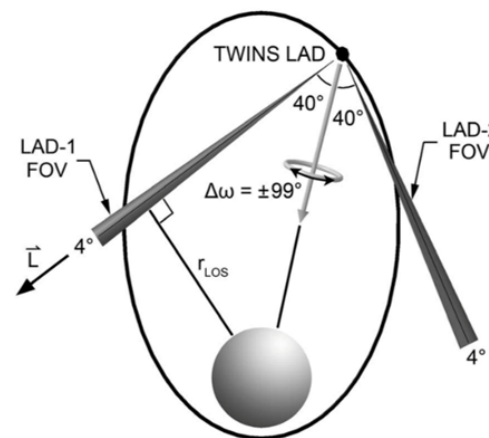
⊙ NASA's Two Wide-angle Imaging Neutral-atom Spectrometers (TWINS) mission provides the capability for **stereoscopically imaging the magnetosphere.**



Source: TWINS SWRI website

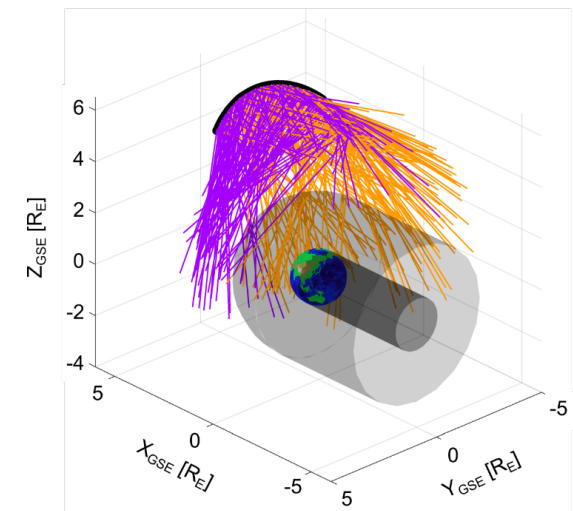
⊙ Each TWINS1/2 has two **Lyman-alpha detectors (LAD)**, optical sensors.

⊙ The selected data in this study is from **11 June 2008**, in order to compare results with those reported by Bailey et al., [2011]



Source: [Bailey et al., 2011]

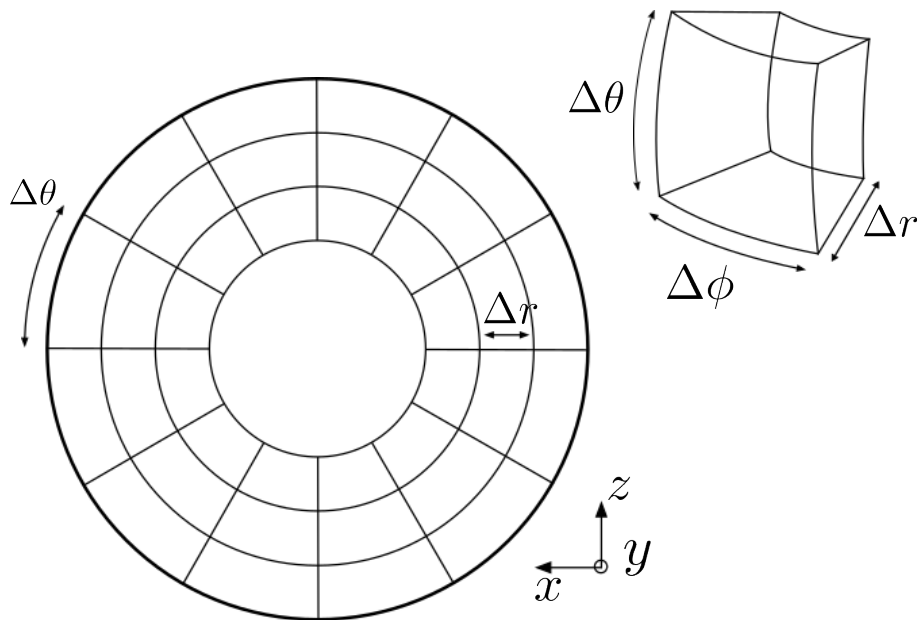
⊙ Since it is quiet-time we assume a **temporally-static** H exosphere.



Discretization of the exospheric volume of interest yields an algebraic linear system.

$$I(\mathbf{r}_i, \hat{\mathbf{n}}_i) = \frac{g^*(\mathbf{r}_i)}{10^6} \int_0^{Lmax} n_H(l) \Psi(\hat{\mathbf{n}}_i) dl + I_{IP}(\hat{\mathbf{n}}_i)$$

- Step 1: Discretize region into J spherical voxels.



- Step 2: Project unknown density function onto J orthonormal basis functions.

$$n_H(r') = \sum_{j=1}^J x_j \delta_{H_j}(r'),$$

$$\delta_{H_j}(r') = \begin{cases} 1 & \text{if } r' \in V_j \\ 0 & \text{else} \end{cases}$$

- Step 3: Rewrite i^{th} measurement of intensity as a linear equation.

$$y(\mathbf{r}_i, \hat{\mathbf{n}}_i) = \sum_{j=1}^J \left[\frac{g^*(\mathbf{r}_i)}{10^6} \Psi(\hat{\mathbf{n}}_i) \int_0^{Lmax} \delta_{H_j}(l) dl \right] x_j$$

$$\mathbf{y} = \mathbf{L}\mathbf{x}$$

$$\mathbf{y} \in \mathbb{R}^M$$

$$\mathbf{x} \in \mathbb{R}^J$$

$$\mathbf{L} \in \mathbb{R}^{M \times J}$$

Solving the estimation problem requires the use of more complex techniques such as regularization

- ⊙ Observation matrix $L \in \mathbb{R}^{M \times J}$, $M \gg J$ and **is not full column rank** (Voxels with out LOS through them).

$$\hat{\mathbf{x}} = \underset{x \geq 0}{\operatorname{argmin}} \Phi(\mathbf{x})$$

- ⊙ Regularization techniques are necessary to obtain a solution.

$$\Phi(\mathbf{x}) = \underbrace{\|L\mathbf{x} - \mathbf{y}\|_2^2}_{\text{Cost Func.}} + \underbrace{\lambda R R P E(\mathbf{x})}_{\text{Regularization term}}$$

Data misfit term

- ⊙ The selected regularization method is **Regularized Robust Positive Estimation**.

$$\lambda R R P E(\mathbf{x}) = \lambda_r \|\mathbf{x}\|_{D_r} + \lambda_\phi \|\mathbf{x}\|_{D_\phi} + \lambda_\theta \|\mathbf{x}\|_{D_\theta}$$

Radial dim. Azimuthal dim. Polar dim.

- ⊙ Includes prior knowledge of **physical structure of the Hydrogen density distributions** for each dimension.

$$\|\mathbf{x}\|_{D_r} = \mathbf{x}^T D_r^T D_r \mathbf{x}$$

Discrete matrix form of
1st and 2nd derivatives

$$D_r \approx \partial^2 / \partial r^2$$

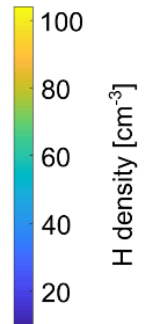
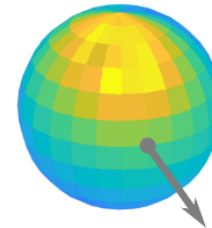
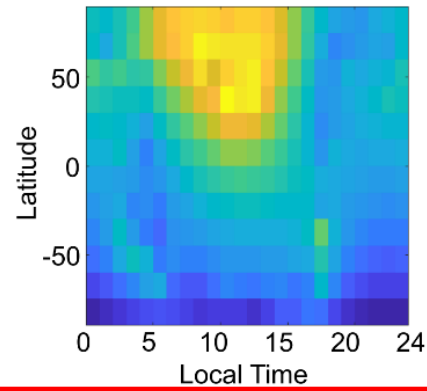
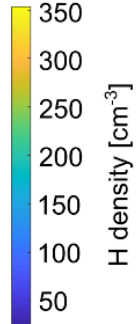
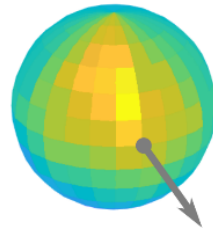
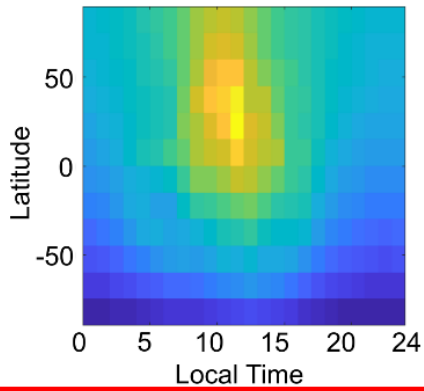
$$D_\phi \approx \partial / \partial \phi$$

$$D_\theta \approx \partial / \partial \theta$$

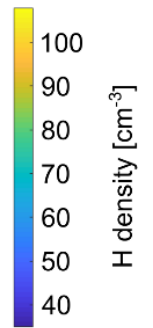
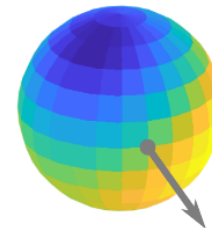
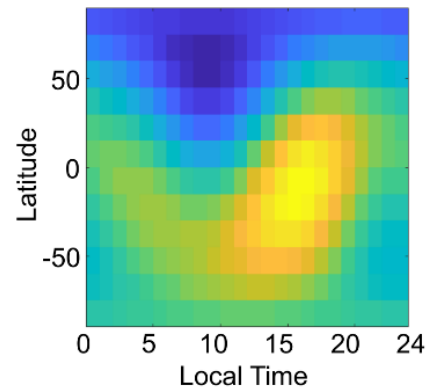
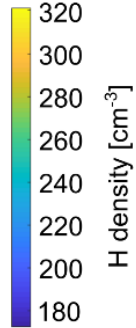
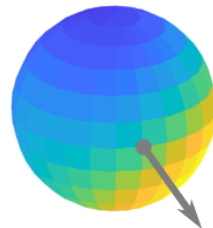
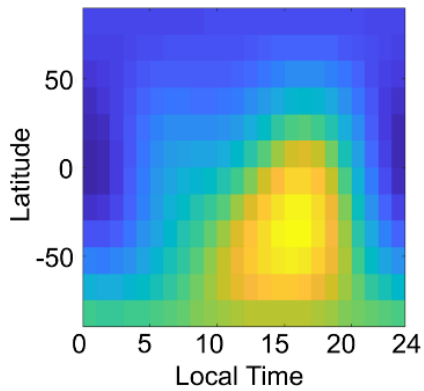
Radial Shell
 $r = 4.125 R_e$

Radial Shell
 $r = 6.375 R_e$

Tomographic reconstruction



Parametric fitting
[Bailey and Gruntman, 2011]



Space-state framework approach for “dynamic tomography” and Kalman Filter as a solver

As exospheric H densities are prone to be dynamic during storm-time, we use the state-space model as a means for time-varying estimation:

Measurement equation:

$$\mathbf{y}_i = H_i \mathbf{x}_i + \mathbf{v}_i$$

Model evolution equation:

$$\mathbf{x}_{i+1} = F_i \mathbf{x}_i + \mathbf{u}_i$$

Inclusion of regularization terms

$$\begin{bmatrix} \mathbf{y}_i \\ 0 \end{bmatrix} = \begin{bmatrix} H_i \\ D_i \end{bmatrix} \mathbf{x}_i + \begin{bmatrix} \mathbf{v}_i \\ \mathbf{w}_i \end{bmatrix}$$

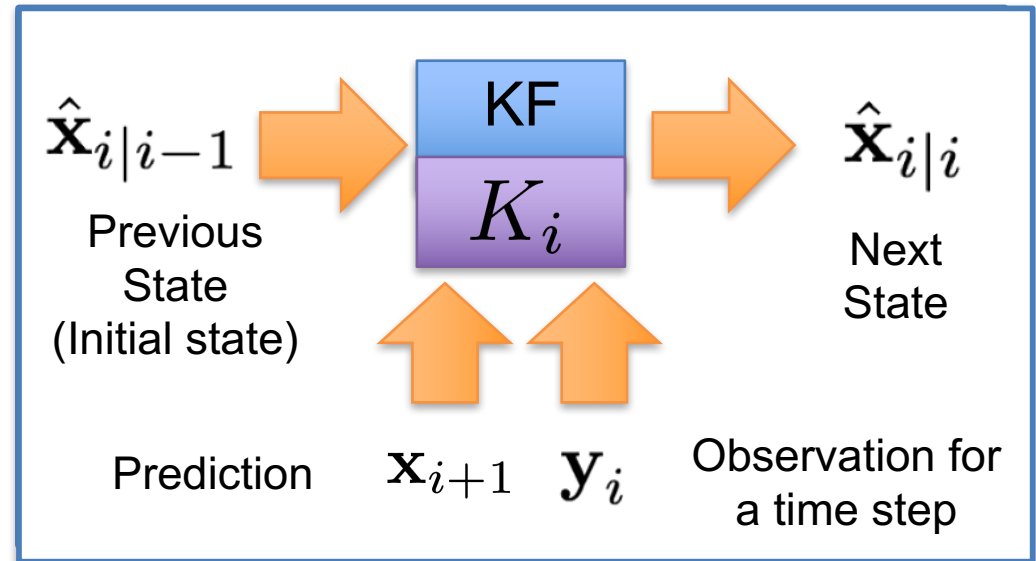
$$\mathbf{y}'_i = H'_i \mathbf{x}_i + v'_i$$

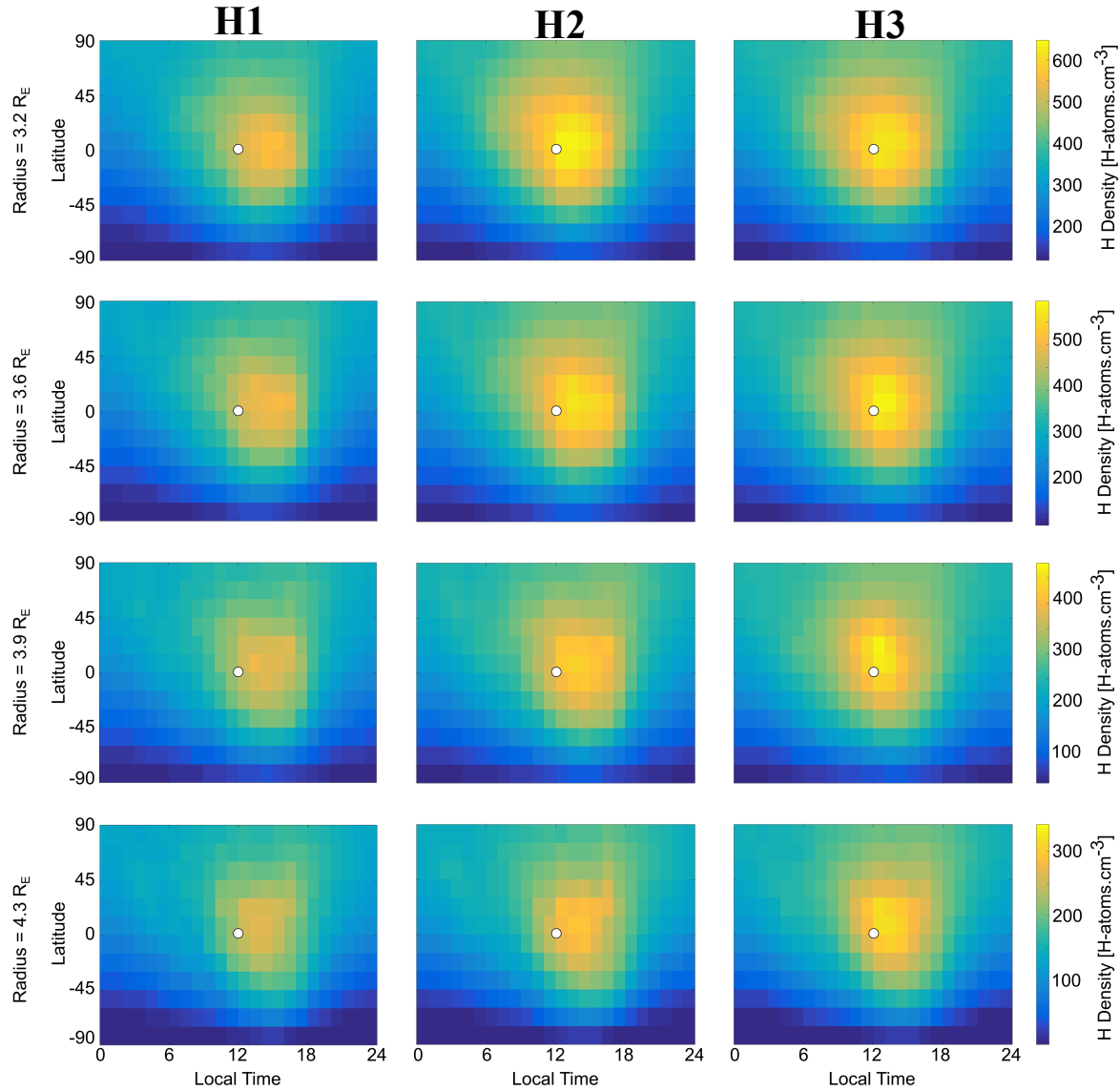
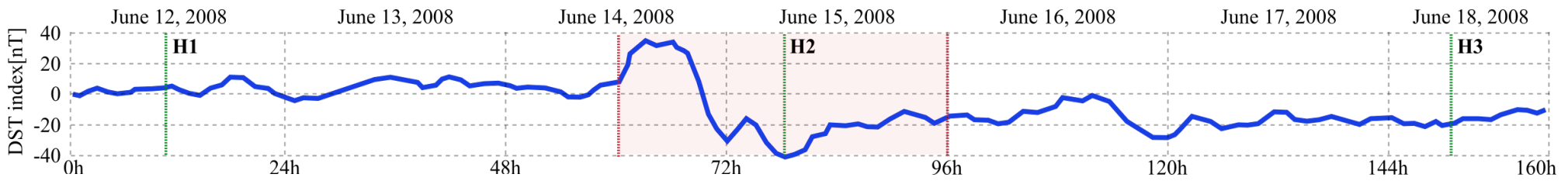
$$R'_i \triangleq \mathbb{E}[\mathbf{v}'_i (\mathbf{v}'_i)^T] = \begin{bmatrix} R_i & 0 \\ 0 & \lambda_i^{-1} I \end{bmatrix}$$

Dynamic tomographic estimation connected to the LMMSE estimation

$$\hat{\mathbf{x}}_{i|i}^d = \underset{\mathbf{x}_i}{\operatorname{argmin}} \left\| \mathbf{y}'_i - H'_i \mathbf{x}_i \right\|_{R'_i}^2 + \left\| \mathbf{x}_i - \hat{\mathbf{x}}_{i|i-1} \right\|_{P_{i|i-1}}^2 + \lambda_\phi \left\| D_\phi \mathbf{x}_i \right\|_2^2 + \lambda_\theta \left\| D_\theta \mathbf{x}_i \right\|_2^2 + \lambda_r \left\| D_r \mathbf{x}_i \right\|_2^2$$

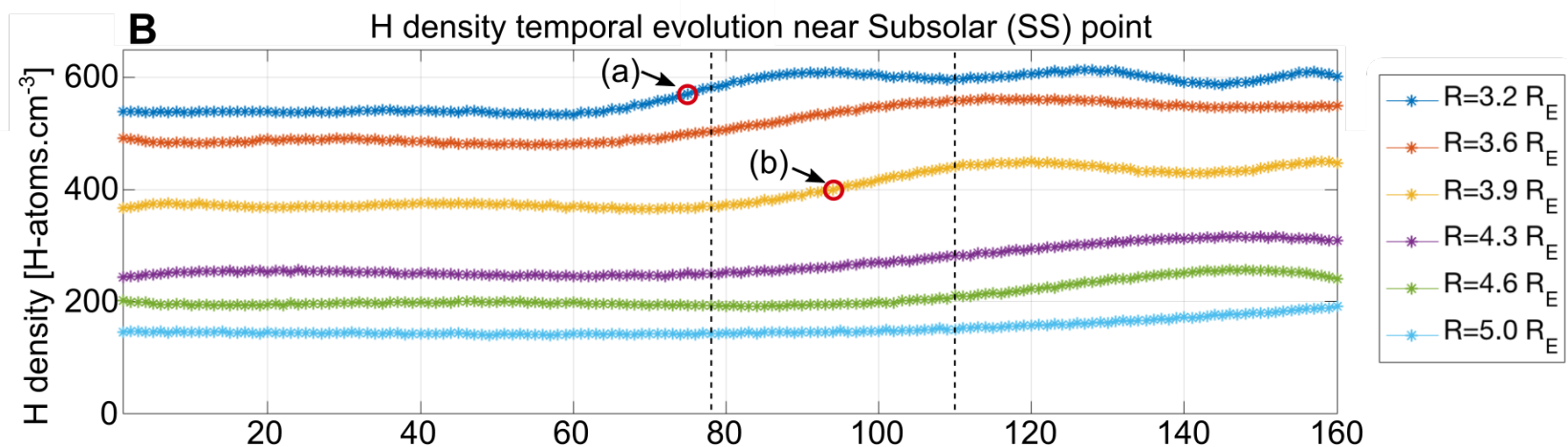
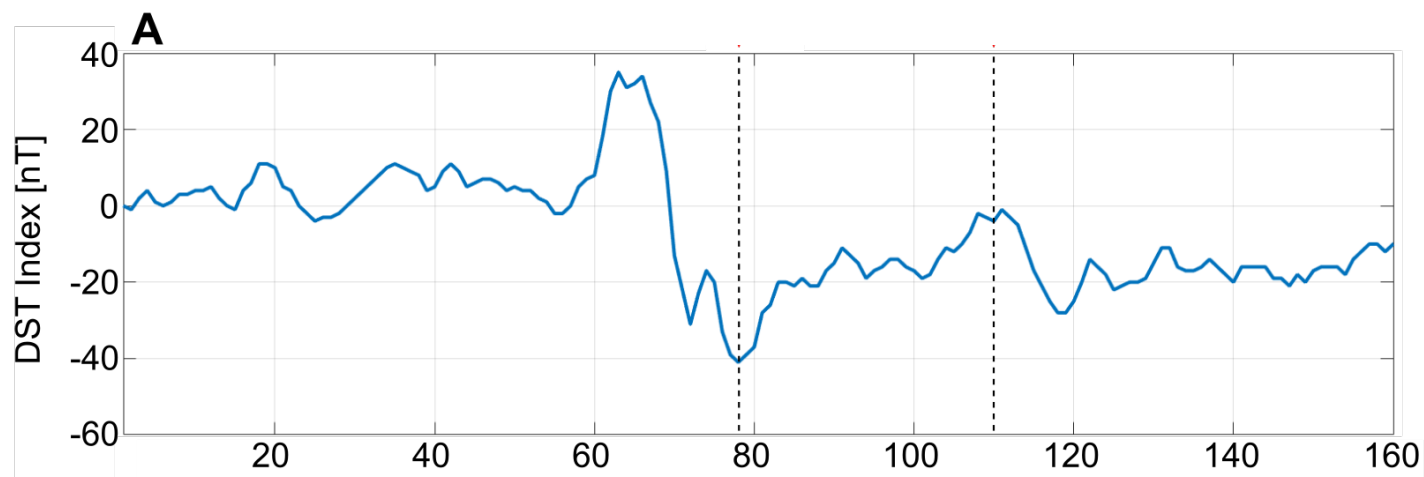
Kalman Filter as solver





⊙ Using KF we have performed 160 dynamic reconstructions during the storm occurred in 15, June, 2008.

⊙ Hydrogen density enhancements during the storm development. Such increments are then translate to higher altitudes with certain delay which suggest a vertical transport or upwelling.



⊙ Hydrogen density enhancement at 3.2 R_E is equal to $\sim 15\%$.

⊙ In the subsolar point, calculations between 3.2 R_E and 3.9 R_E profiles result in a exospheric wind of $\sim 60\text{m/s}$.

[Cucho-Padin & Waldrop, GRL, 2019]

Summary

- ⊙ Dynamic tomography based on TWINS observations shows that H density increases abruptly in response to the geomagnetic storm on 15 June, 2008. The increment rate and its magnitude varying with distance from Earth.
- ⊙ Density increases begin soonest in the innermost exospheric region in the reconstruction (3.2 RE) and reach a peak density fastest there. Overall density enhancements of **~15%** are observed at **3.2 RE**. Recovery to pre-storm values is very slow.
- ⊙ Also, analysis of the radial structure for the subsolar point yielded a **~60 m/s** wind in vertical direction.
- ⊙ Further work :
 1. Conduct similar experiments during a strong geomagnetic storm.
 2. Use of tomographically-reconstructed H densities in ring current and plasmasphere analysis during storm-time.

References

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